### CS 536 – Montana State University

## Bayesian Learning Chapter 6 of Tom Mitchell's Machine Learning Book

**Sections 6.5-6.10** 

Neal Richter – March 27th 2006

Slides adapted from Mitchell's lecture notes and Dr. Geehyuk Lee's Machine Learning class at ICU

### Bayes Theorem (Review from last week)

$$P(h|D) = \frac{P(D|h)P(h)}{P(D)}$$
 $P(h) = \text{prior probability of hypothesis } h$ 
 $P(D) = \text{prior probability of training data } D$ 
 $P(h|D) = \text{probability of } h \text{ given } D$ 
 $P(D|h) = \text{probability of } D \text{ given } h$ 

- Note a symmetry in the equation:
  - The equation remains in the same form if you exchange h and D.
- Can you explain the meaning of P(D)?

### Choosing Hypotheses (Review from last week)

- Maximum a posteriori (MAP) hypothesis:

$$h_{MAP} = \arg \max_{h \in H} P(h|D)$$

$$= \arg \max_{h \in H} \frac{P(D|h)P(h)}{P(D)}$$

$$= \arg \max_{h \in H} P(D|h)P(h)$$

- Maximum likelihood (ML) hypothesis:

$$h_{ML} = \arg\max_{h_i \in H} P(D|h_i)$$

• When do these two become the same?

### Basic Formulas for Probabilities (Review from last week)

Product Rule:

$$P(A \wedge B) = P(A|B)P(B) = P(B|A)P(A)$$

Sum Rule:

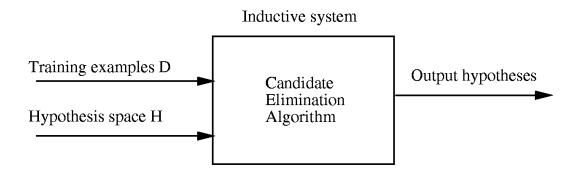
$$P(A \lor B) = P(A) + P(B) - P(A \land B)$$

Theorem of total probability:

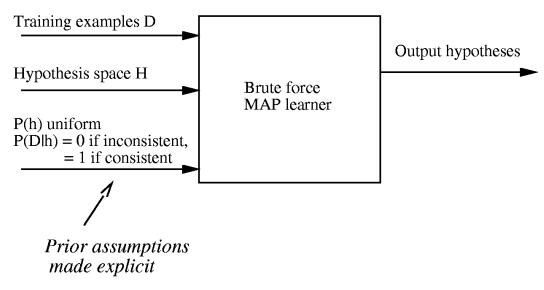
$$P(B) = \sum_{i=1}^{n} P(B|A_i)P(A_i)$$

if  $A_1, \ldots, A_n$  are mutually exclusive with  $\sum_{i=1}^n P(A_i) = 1$ .

# **Characterizing Concept Learning by Equivalent MAP Learners** (Review from last week)



Equivalent Bayesian inference system



### **Learning to Predict Probabilities**

Consider predicting survival probability from patient data.

- (Stochastic) Examples:  $\langle x_i, d_i \rangle, d_i \in \{0, 1\}$
- Need a non-deterministic classifier, but MLP is not.
- Instead, MLP that outputs a probability given  $x_i$ .
- Conditional probability:

$$P(D|h) = \prod_{i=1}^{m} P(x_i, d_i|h) = \prod_{i=1}^{m} P(d_i|h, x_i)P(x_i)$$

• Note  $P(d_i|h,x_i)$  is either 0 or 1.

$$P(d_i|h, x_i) = h(x_i)^{d_i} (1 - h(x_i))^{1 - d_i}$$

$$P(D|h) = \prod_{i=1}^{m} h(x_i)^{d_i} (1 - h(x_i))^{1 - d_i} P(x_i)$$

### **Learning to Predict Probabilities (2)**

• ML hypothesis:

$$h_{ML} = \arg\max_{h \in H} \prod_{i=1}^{m} h(x_i)^{d_i} (1 - h(x_i))^{1 - d_i} P(x_i)$$

• Note that  $P(x_i)$  is independent of h.

$$h_{ML} = \arg\max_{h \in H} \prod_{i=1}^{m} h(x_i)^{d_i} (1 - h(x_i))^{1 - d_i}$$

$$h_{ML} = \arg\max_{h \in H} \sum_{i=1}^{m} d_i \ln h(x_i) + (1 - d_i) \ln(1 - h(x_i))$$

- The quantity to be maximized look like an entropy.
- It is in fact  $-(const) \times (crossentropy)$
- Cross entropy represents similarity between two probability distributions.

#### Gradient Search to Maximize Likelihood in NNs

• Let G(h, D) the quantity to be maximized.

$$\frac{\partial G(h, D)}{\partial w_{jk}} = \sum_{i=1}^{m} \frac{\partial G(h, D)}{\partial h(x_i)} \frac{\partial h(x_i)}{\partial w_{jk}}$$

$$= \sum_{i=1}^{m} \frac{\partial (d_i \ln h(x_i) + (1 - d_i) \ln(1 - h(x_i)))}{\partial h(x_i)} \frac{\partial h(x_i)}{\partial w_{jk}}$$

$$= \sum_{i=1}^{m} \frac{d_i - h(x_i)}{h(x_i)(1 - h(x_i))} \frac{\partial h(x_i)}{\partial w_{jk}}$$

• For a single-layer NN

$$\frac{\partial h(x_i)}{\partial w_{jk}} = \sigma'(x_i)x_{ijk} = h(x_i)(1 - h(x_i))x_{ijk}$$

$$\frac{\partial G(h,D)}{\partial w_{jk}} = \sum_{i=1}^{m} (d_i - h(x_i)) x_{ijk}$$

• This is going to take us to something similar to LMS learning rule...

### **Comparison to NN Sigmoid Update Rule**

Consider predicting survival probability from patient data

Training examples  $\langle x_i, d_i \rangle$ , where  $d_i$  is 1 or 0

Want to train neural network to output a probability given  $x_i$  (not a 0 or 1)

In this case can show

$$h_{ML} = \underset{h \in H}{\operatorname{argmax}} \sum_{i=1}^{m} d_i \ln h(x_i) + (1 - d_i) \ln(1 - h(x_i))$$

Weight update rule for a sigmoid unit:

$$w_{jk} \leftarrow w_{jk} + \Delta w_{jk}$$

where

$$\Delta w_{jk} = \eta \sum_{i=1}^{m} (d_i - h(x_i)) x_{ijk}$$

$$\Delta w_{jk} = \eta \sum_{i=1}^{m} h(x_i) (1 - h(x_i) (d_i - h(x_i)) x_{ijk}$$
 (With sigmoid derivative)

### Minimum Description Length Principle

$$h_{MAP} = \arg \max_{h \in H} P(D|h)P(h)$$

$$= \arg \max_{h \in H} \log_2 P(D|h) + \log_2 P(h)$$

$$= \arg \min_{h \in H} - \log_2 P(D|h) - \log_2 P(h) \quad (1)$$

Interesting fact from information theory:

The optimal (shortest expected coding length) code for an event with probability p is  $-\log_2 p$  bits.

So interpret (1):

- $-\log_2 P(h)$  is length of h under optimal code
- $-\log_2 P(D|h)$  is length of D given h under optimal code
- $\rightarrow$  prefer the hypothesis that minimizes length(h) + length(misclassifications)

### **Minimum Description Length Principle (2)**

- MDL: prefer the hypothesis h that minimizes

$$h_{MDL} = \arg\min_{h \in H} L_{C_1}(h) + L_{C_2}(D|h)$$

where  $L_C(x)$  is the description length of x under encoding C.

- Occam's razor: prefer the shortest hypothesis

 Does this mean that a hypothesis chosen by the MDL principle will be the MAP hypothesis?

#### Most Probable Classification of New Instances

- So far we've sought the most probable hypothesis  $h_{MAP}$  given the data D.
- Given new instance x, what is its most probable classification?
- Is  $h_{MAP}(x)$  the most probable classification?

#### Consider:

• Three possible hypotheses:

$$P(h_1|D) = .4, P(h_2|D) = .3, P(h_3|D) = .3$$

• Given new instance x,

$$h_1(x) = +, h_2(x) = -, h_3(x) = -$$

• What's most probable classification of x?

### **Bayes Optimal Classifier**

Bayes optimal classification:

$$\arg\max_{v_j \in V} P(v_j|D) = \arg\max_{v_j \in V} \sum_{h_i \in H} P(v_j|h_i)P(h_i|D)$$

In our example,

$$\sum_{h_i \in H} P(+|h_i)P(h_i|D) = 0.4 + 0 + 0 = 0.4$$

$$\sum_{h_i \in H} P(-|h_i)P(h_i|D) = 0 + 0.3 + 0.3 = 0.6$$

Therefore,

$$\arg\max_{v_j \in V} \sum_{h_i \in H} P(v_j|h_i)P(h_i|D) = -$$

### Gibbs Classifier/Sampler

Bayes optimal classifier provides best result, but can be expensive if many hypotheses.

#### Gibbs algorithm:

- Choose one hypothesis at random, according to P(h|D)
- Use this to classify new instance

Surprising fact: if target concepts are drawn at random from H according to priors on H, then

$$E[error_{Gibbs}] \le 2E[error_{BayesOptimal}]$$

For uniform prior distribution over H,

- Pick any hypothesis from VS, with uniform probability
- Its expected error no worse than twice Bayes optimal

### **Naive Bayes Classifier**

Along with decision trees, neural networks, nearest nbr, one of the most practical learning methods.

#### When to use

- Moderate or large training set available
- Attributes that describe instances are conditionally independent given classification

### Successful applications:

- Diagnosis
- Classifying text documents

### **Naive Bayes Classifier (2)**

Assume target function  $f: X \to V$ , where each instance x described by attributes  $\langle a_1, a_2 \dots a_n \rangle$ .

Most probable value of f(x):

$$v_{MAP} = \arg \max_{v_j \in V} P(v_j | a_1, a_2 \dots a_n)$$
  
 $v_{MAP} = \arg \max_{v_j \in V} \frac{P(a_1, a_2 \dots a_n | v_j) P(v_j)}{P(a_1, a_2 \dots a_n)}$   
 $= \arg \max_{v_j \in V} P(a_1, a_2 \dots a_n | v_j) P(v_j)$ 

Naive Bayes classifier:

$$v_{NB} = \arg\max_{v_j \in V} P(v_j) \prod_i P(a_i|v_j)$$

Naive Bayes assumption:

$$P(a_1, a_2 \dots a_n | v_j) = \prod_i P(a_i | v_j)$$

### **Naive Bayes Algorithm**

 $Naive\_Bayes\_Learn(examples)$ 

For each target value  $v_j$ 

$$\hat{P}(v_j) \leftarrow \text{estimate } P(v_j)$$

For each attribute value  $a_i$  of each attribute a

$$\hat{P}(a_i|v_j) \leftarrow \text{estimate } P(a_i|v_j)$$

Classify\_New\_Instance(x)

$$v_{NB} = \operatorname*{argmax}_{v_j \in V} \hat{P}(v_j) \prod_{a_i \in x} \hat{P}(a_i | v_j)$$

### **Naive Bayes: Example**

Consider *PlayTennis* again, and new instance

$$\langle Outlk = sun, Temp = cool, Humid = high, Wind = strong \rangle$$

Want to compute:

$$v_{NB} = \arg\max_{v_j \in V} P(v_j) \prod_i P(a_i|v_j)$$

$$P(y) P(sun|y) P(cool|y) P(high|y) P(strong|y) = .005$$

$$P(n) P(sun|n) P(cool|n) P(high|n) P(strong|n) = .021$$

$$\rightarrow v_{NB} = n$$

### **Naive Bayes: Subtleties**

- Conditional independence assumption is often violated

$$P(a_1, a_2 \dots a_n | v_j) = \prod_i P(a_i | v_j)$$

...but it works surprisingly well anyway.

- Estimated posteriors  $\hat{P}(v_j|x)$  need not be correct; need only that

$$\arg\max_{v_j\in V} \hat{P}(v_j) \prod_i \hat{P}(a_i|v_j) = \arg\max_{v_j\in V} P(v_j) P(a_1, \dots, a_n|v_j)$$

- See [Domingos & Pazzani, 1996] for analysis.
- Naive Bayes posteriors often unrealistically close to 1 or 0

### Naive Bayes: Subtleties (2)

- What if none of the training instances with target value  $v_j$  have attribute value  $a_i$ ? Then,

$$\hat{P}(a_i|v_j) = 0$$
, and... $\hat{P}(v_j) \prod_i \hat{P}(a_i|v_j) = 0$ 

- Typical solution is Bayesian estimate for  $\hat{P}(a_i|v_j)$ 

$$\hat{P}(a_i|v_j) \leftarrow \frac{n_c + mp}{n + m}$$

- n is number of training examples for which  $v = v_j$ ,
- $n_c$  number of examples for which  $v = v_j$  and  $a = a_i$
- p is prior estimate for  $\hat{P}(a_i|v_j)$
- m is weight given to prior (i.e. number of "virtual" examples)

### **Learning to Classify Text**

- Target concept:

Interesting?:  $Document \rightarrow \{+, -\}$ 

- 1. Represent each document by vector of words.
  - One attribute per word position in document
- 2. Learning: Use training examples to estimate
  - P(+)
  - $\bullet$  P(-)
  - $\bullet$  P(doc|+)
  - $\bullet P(doc|-)$

### **Learning to Classify Text**

- Naive Bayes conditional independence assumption:

$$P(doc|v_j) = \prod_{i=1}^{length(doc)} P(a_i = w_k|v_j)$$

- where  $P(a_i = w_k | v_j)$  is probability that word in position i is  $w_k$ , given  $v_j$
- One more assumption:

$$P(a_i = w_k | v_j) = P(a_m = w_k | v_j), \forall i, m$$

- What does this mean?
- Is this a plausible assumption?

### Learn\_Naïve\_Bayes\_Text (Examples, V)

- 1. Collect all words and other tokens that occur in Examples
  - $Vocabulary \leftarrow$  all distinct words and other tokens in Examples
- 2. Calculate the required  $P(v_j)$  and  $P(w_k|v_j)$  probability terms
  - For each target value  $v_i$  in V do
    - $docs_j \leftarrow \text{subset of } Examples \text{ for which the target}$ value is  $v_j$
    - $-P(v_j) \leftarrow \frac{|docs_j|}{|Examples|}$
    - $Text_j \leftarrow$  a single document created by concatenating all members of  $docs_j$
    - $-n \leftarrow \text{total number of words in } Text_j \text{ (counting duplicate words multiple times)}$
    - for each word  $w_k$  in Vocabulary
      - \*  $n_k \leftarrow \text{number of times word } w_k \text{ occurs in } Text_j$
      - \*  $P(w_k|v_j) \leftarrow \frac{n_k+1}{n+|Vocabulary|}$

### Classify\_Naïve\_Bayes\_Text (*Doc*)

Return the estimated target value for the document Doc.

- $positions \leftarrow all word positions in <math>Doc$  that contain tokens found in Vocabulary
- Return  $v_{NB}$ , where

$$v_{NB} = \arg\max_{v_j \in V} P(v_j) \prod_{i \in positions} P(a_i|v_j)$$

### **Twenty Newsgroups (Joachims, 1996)**

- 1000 training documents from each of 20 groups → 20,000
- Use two third of them in learning to classify new documents according to which newsgroup it came from.

#### Newsgroups:

- comp.graphics, misc.forsale, comp.os.ms-windows.misc, rec.autos, comp.sys.ibm.pc.hardware, rec.motorcycles, comp.sys.mac.hardware, rec.sport.baseball, comp.windows.x, rec.sport.hockey, alt.atheism, sci.space, soc.religion.christian, sci.crypt, talk.religion.misc, sci.electronics, talk.politics.mideast, sci.med, talk.politics.misc, talk.politics.guns
- Naive Bayes: 89% classification accuracy
- Random guess: ?

### An article from rec.sport.hockey

Path: cantaloupe.srv.cs.cmu.edu!das-news.harvard.edu!ogicse!uwm.edu

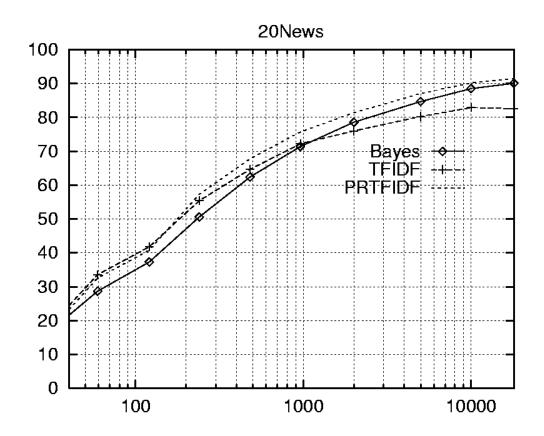
From: xxx@yyy.zzz.edu (John Doe)

Subject: Re: This year's biggest and worst (opinion)...

Date: 5 Apr 93 09:53:39 GMT

I can only comment on the Kings, but the most obvious candidate for pleasant surprise is Alex Zhitnik. He came highly touted as a defensive defenseman, but he's clearly much more than that. Great skater and hard shot (though wish he were more accurate). In fact, he pretty much allowed the Kings to trade away that huge defensive liability Paul Coffey. Kelly Hrudey is only the biggest disappointment if you thought he was any good to begin with. But, at best, he's only a mediocre goaltender. A better choice would be Tomas Sandstrom, though not through any fault of his own, but because some thugs in Toronto decided ...

### **Learning Curve for 20 Newsgroups**



Accuracy vs. Training set size (1/3 withheld for test) (Note that the x-axis in log scale)