# $P$ and NP CSCI 338 

## Announcements

- Test 2. (AVG = 72\%, MED = 85\%)
- Project 2. (AVG = 80\%, MED = 100\%)

> Computability: What's solvable by computers.

## January



## Computational Complexity

Determining the amount of resources required to accomplish some task (solve a problem).

- Time (most common)
- Space (close behind)
- Power (sensor networks, spacecraft, military)
- Network (Netflix, loT)


## Definitions

Definition: For TM $M$, the running time of $\boldsymbol{M}$ is the function $f: \mathbb{N} \rightarrow \mathbb{N}$, where $f(n)$ is the maximum number of steps $M$ used on any input of length $n$.

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Definition: For TM $M$, the running time of $\boldsymbol{M}$ is the function $f: \mathbb{N} \rightarrow \mathbb{N}$, where $f(n)$ is the maximum number of steps $M$ used on any input of length $n$.

Definition: Let $f$ and $g$ be functions $f, g: \mathbb{N} \rightarrow \mathbb{R}^{+}$, $\boldsymbol{f}(\boldsymbol{n}) \in \boldsymbol{O}(\boldsymbol{g}(\boldsymbol{n}))$ if $\exists$ positive integers $c$ and $n_{0}$ such that $\forall n \geq n_{0}, f(n) \leq c g(n)$.

Definition: Let $t: \mathbb{N} \rightarrow \mathbb{R}^{+}$be a function. The time complexity class, $\operatorname{TIME}(\boldsymbol{t}(\boldsymbol{n}))$, is the collection of all languages that are decidable by an $O(t(n))$ time TM.

Definition: $\boldsymbol{P}$ is the set of languages that are decidable in polynomial time on a deterministic single-tape TM.

Properties of $P$ :

$$
P=\bigcup_{k} \operatorname{TIME}\left(n^{k}\right)
$$

- Inclusion in $P$ holds for all computational models polynomially equivalent to deterministic, single-tape TMs.
- Roughly corresponds to problems solvable by a computer.

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## Why Polynomial?

Given a problem of size $n$...
Algorithm A
solves it in $n^{2}$
seconds

Algorithm B solves it in $2^{n}$ seconds

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A solves in $1 \mathrm{~min} \Rightarrow A$ solves in $60 \mathrm{sec} \Rightarrow n \approx 7.7$
$B$ solves in $5 \mathrm{~min} \Rightarrow B$ solves in $300 \mathrm{sec} \Rightarrow n \approx 8.2$

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Given a problem of size $n$...
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Would you rather have an hour of compute time for algorithm $A$, or 10 billion years of compute time for algorithm $B$ ?

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A solves in $1 \mathrm{hr} \Rightarrow$ A solves in $3600 \mathrm{sec} \Rightarrow n=60$

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A solves in $1 \mathrm{hr} \Rightarrow$ A solves in $3600 \mathrm{sec} \Rightarrow n=60$ $B$ solves in 10B yr $\Rightarrow B$ solves in lots of $\sec \Rightarrow n \approx 58$

## Why Polynomial?



Polynomial time algorithms are usually useful, exponential time algorithms are rarely useful

## PATH

Claim: $P A T H=\{\langle G, s, t\rangle: G=(V, E)$ is a directed graph with a path from $s$ to $t\} \in P$.

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& N=\text { on input }\langle G, s, t\rangle \\
& 1 .
\end{aligned}
$$

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Claim: PATH $=\{\langle G, s, t\rangle: G=(V, E)$ is a directed graph with a path from $s$ to $t\} \in P$.

Proof: Build a polynomial time decider.
$N=$ on input $\langle G, s, t\rangle$

1. Mark $s$.
2. 

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N=\text { on input }\langle G, s, t\rangle
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1. Mark $s$.
2. Repeat until no new nodes are marked:
3. For each $e=(a, b) \in E$, if $a$ is marked, mark $b$.
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Need to show N is a decider and runs in polynomial time.

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Claim: $P A T H=\{\langle G, s, t\rangle: G=(V, E)$ is a directed graph with a path from $s$ to $t\} \in P$.

Proof: Build a polynomial time decider.
Suppose $|V|=n$.
$N=$ on input $\langle G, s, t\rangle$

1. Mark $s$.
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Proof: Build a polynomial time decider.

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\text { Suppose }|\hat{V}|=n
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N=\text { on input }\langle G, s, t\rangle
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? $\longrightarrow$ 1. Mark $s$.
2. Repeat until no new nodes are marked:
3. For each $e=(a, b) \in E$, if $a$ is marked, mark $b$.
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\text { Suppose }|V|=n
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N=\text { on input }\langle G, s, t\rangle
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$\boldsymbol{O}(\mathbf{1}) \longrightarrow$ 1. Mark $s$.
2. Repeat until no new nodes are marked:
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& \text { Suppose }|V|=n \text {. } \\
& N=\text { on input }\langle G, s, t\rangle
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$\boldsymbol{O}(\mathbf{1}) \longrightarrow$ 1. Mark $s$.
2. Repeat until no new nodes are marked:
$? \longrightarrow 3$. For each $e=(a, b) \in E$, if $a$ is marked, mark $b$.
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Claim: $P A T H=\{\langle G, s, t\rangle: G=(V, E)$ is a directed graph with a path from $s$ to $t\} \in P$.
At most, how many edges are in an undirected graph with $n$ vertices? What graph has the most number of edges?

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At most, how many edges are in an undirected graph with $n$ vertices? What graph has the most number of edges?

Complete graph (every pair of vertices have an edge).


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Complete graph (every pair of vertices have an edge).
How many edges does a complete graph with $n$ vertices have? How many edges leave each vertex?

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How many edges does a complete graph with $n$ vertices have?
How many edges leave each vertex? $n-1$
How much does that all add up to?

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How many edges does a complete graph with $n$ vertices have?
How many edges leave each vertex? $n-1$
How much does that all add up to? $n(n-1)$
Did we double count any edges?

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How many edges does a complete graph with $n$ vertices have?
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How much does that all add up to? $n(n-1)$
Did we double count any edges? Yes
So how many edges are there?

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How much does that all add up to? $n(n-1)$
Did we double count any edges? Yes
So how many edges are there? $\frac{n(n-1)}{2} \in O\left(n^{2}\right)$

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What if it is directed?
Need to show N is a decider and runs in polynomial time.

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How many edges does a complete graph with $n$ vertices have?
How many edges leave each vertex? $n-1$
How much does that all add up to? $n(n-1)$
Did we double count any edges? Yes
So how many edges are there? $\frac{n(n-1)}{2} \in O\left(n^{2}\right)$
What if it is directed? $n(n-1) \in O\left(n^{2}\right)$ (no double counts)
Need to show N is a decider and runs in polynomial time.

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$\boldsymbol{O}(\mathbf{1}) \longrightarrow$ 1. Mark $s$.
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\text { Suppose }|\hat{V}|=n
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$\boldsymbol{O}(\mathbf{1}) \longrightarrow$ 1. Mark $s$.
$\boldsymbol{O}(\boldsymbol{n}) \longrightarrow 2$. Repeat until no new nodes are marked:
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$\boldsymbol{O}\left(\boldsymbol{n}^{\mathbf{2}}\right) \longrightarrow 3$. For each $e=(a, b) \in E$, if $a$ is marked, mark $b$.
$? \longrightarrow 4$. If $t$ is marked, accept. Otherwise, reject.
Need to show N is a decider and runs in polynomial time.

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Claim: $P A T H=\{\langle G, s, t\rangle: G=(V, E)$ is a directed graph with a path from $s$ to $t\} \in P$.

Proof: Build a polynomial time decider.

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$\boldsymbol{O}\left(\boldsymbol{n}^{2}\right) \longrightarrow 3$. For each $e=(a, b) \in E$, if $a$ is marked, mark $b$.
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Claim: $P A T H=\{\langle G, s, t\rangle: G=(V, E)$ is a directed graph with a path from $s$ to $t\} \in P$.

Proof: Build a polynomial time decider. Suppose $|V|=n$.

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N=\text { on input }\langle G, s, t\rangle
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$\boldsymbol{O}(\mathbf{1}) \longrightarrow$ 1. Mark $s$.
$\boldsymbol{O}(\boldsymbol{n}) \longrightarrow 2$. Repeat until no new nodes are marked:
$\boldsymbol{O}\left(\boldsymbol{n}^{2}\right) \longrightarrow 3$. For each $e=(a, b) \in E$, if $a$ is marked, mark $b$.
$\boldsymbol{O}(\mathbf{1}) \longrightarrow 4$. If $t$ is marked, accept. Otherwise, reject.
N is a decider and runs in $O\left(n^{3}\right)$ time, therefore $P A T H \in P$.

