# Approximation Algorithms CSCI 338

#### Vertex Cover

Vertex Cover: Given graph, find the smallest subset of vertices such that every edge in the graph has at least one vertex in the subset.

#### **Optimization Problem.**



# Vertex Cover – Algorithm

Vertex Cover: Given graph, find the smallest subset of vertices such that every edge in the graph has at least one vertex in the subset.

Algorithm:

while uncovered edge exists
 select both vertices from uncovered edge



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Consider a set of edges,  $E' \subset E$ , that do not share vertices. Is there a relationship between the minimum vertex cover and |E'|?



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If we selected fewer than one vertex per edge, we would not have a vertex cover, because that edge would not be covered!



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Consider every of order  $E' \in E$  that do not characterized to there a relation We cannot find optimal vertex covers in poly time unless P = NP, but this Does the algorithm is at worst 2-times optimal. do not share vertices?

$$\mathsf{ALG} = 2 |E'|$$

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Consider that of order 
$$E' \in E$$
 that do not chose vertices is there  
a relative vertices is approximable within the  
bound  $2 - \frac{\log \log |V|}{2 \log |V|}$  and inapproximable  
do not within the bound 1.3606.  
ALG = 2 |E'|

 $\Rightarrow$  ALG = 2  $|E'| \le 2$  OPT  $\Rightarrow$  ALG  $\le 2$  OPT

Does the approximation algorithm for Vertex Cover give an approximation algorithm for Independent Set?





Vertex Cover

Independent Set

#### **Minimum Vertex Cover = Maximum Independent Set**

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**Minimum Vertex Cover = Maximum Independent Set** 

$$ALG_{VC} \leq 2 \ OPT_{VC} \Longrightarrow n - ALG_{VC} \geq \frac{1}{?} \ OPT_{IS}$$

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Complete Bipartite Graph



Independent Set is inapproximable  
within the bound 
$$|V|^{1-\varepsilon}$$
, for any  $\varepsilon > 0$ .  
 $n \le 2\frac{n}{2}$   $0 \ge \frac{1}{2}\frac{n}{2}$ 



**Computability Hierarchy** 





TSP: Given a weighted graph, find a least cost cycle that visits each vertex exactly once.

Algorithm<mark>?</mark>

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Suppose *H* is an  $\alpha$ -approximation algorithm for TSP. I.e. H(G) = Hamiltonian Cycle  $C_H$ , where  $cost(C_H) \le \alpha cost(C_{OPT})$ 

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```
<insert name>(G)
Let C<sub>H</sub> = H(G)
if C<sub>H</sub> == null
   return false
else
   return true
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Metric TSP: Given a complete weighted graph that satisfies the triangle inequality, find a least cost cycle that visits each vertex exactly once.

Triangle Inequality:  $cost(u, v) \le cost(u, w) + cost(w, v)$ 





Find some structure that is:

- 1. Easy to compute.
- 2. Related to TSP.
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What is this? Spanning Tree

Relationship between OPT and cost of MST?





Relationship between OPT and cost of MST?  $cost(MST) \le OPT$ 

How to turn MST into a cycle?





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How to turn MST into a cycle? What is the cost of this cycle? ALG = 2 cost(MST)

Relationship between ALG and OPT?





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Relationship between ALG and OPT? ALG =  $2 \operatorname{cost}(MST) \le 2 \operatorname{OPT}$ 

Any problems?





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Relationship between ALG and OPT? ALG =  $2 \operatorname{cost}(MST) \le 2 \operatorname{OPT}$ 

How can we eliminate double visits (without messing up the cost)?





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Relationship between ALG and OPT? ALG =  $2 \operatorname{cost}(MST) \le 2 \operatorname{OPT}$ 

How can we eliminate double visits (without messing up the cost)?

Skip to next unvisited vertex. Can only decrease cost (triangle inequality).  $dist(u, v) \le dist(u, w) + dist(w, v)$ 





Metric TSP: Given a complete weighted graph that satisfies the triangle inequality, find a least cost cycle that visits each vertex exactly once.

 $ALG = 2 \operatorname{cost}(MST) \le 2 \operatorname{OPT}$ 



