# Inapproximability CSCI 532

#### Test 3 Logistics

- 1. During class on Thursday 11/20.
- 2. You can bring your book and any notes you would like, but no electronic devices.
- 3. You may assume anything proven in class or on homework.
- 4. Three questions (10 points):
  - 1) Approximation algorithm (5 points).
  - 2) Special case (2 points).
  - 3) Tightness example (3 points).

# **Project Logistics**

- 1. Report due 12/2 (first day of presentations).
- 2. Presentation schedule posted.
- 3. 15 minutes <u>maximum</u> presentation time. Leave a couple minutes for questions.
- 4. Attend other peoples' presentations. If attendance plummets, I may have to factor attendance into project grades.

## **Project Logistics**

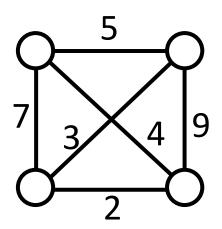
- 1. Report due 12/2 (first day of presentations).
- 2. Presentation schedule posted.
- 3. 15 minutes <u>maximum</u> presentation time. Leave a couple minutes for questions.
- 4. Attend other peoples' presentations. If attendance plummets, I may have to factor attendance into project grades.

Also, please do the course evaluation: https://faculty.campuslabs.com/eval-home/direct/8521795

#### Travelling Salesman Problem

TSP: Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city once and returns to the origin city?

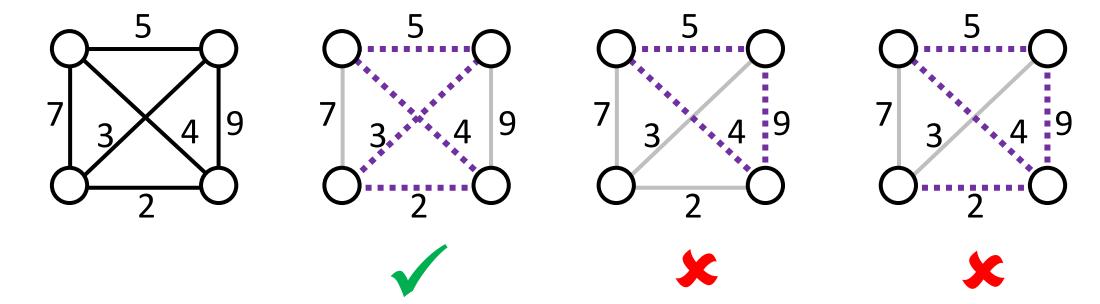
**∈ NP-Complete** 



#### Travelling Salesman Problem

TSP: Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city once and returns to the origin city?

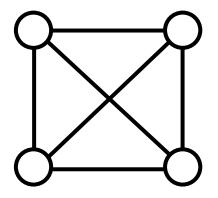
#### **∈ NP-Complete**



# Hamiltonian Cycle Problem

Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.

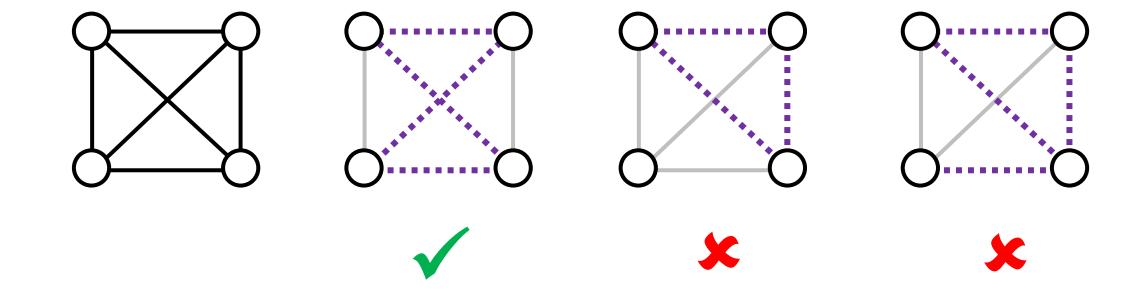
**∈ NP-Complete** 



# Hamiltonian Cycle Problem

Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.

## **∈ NP-Complete**



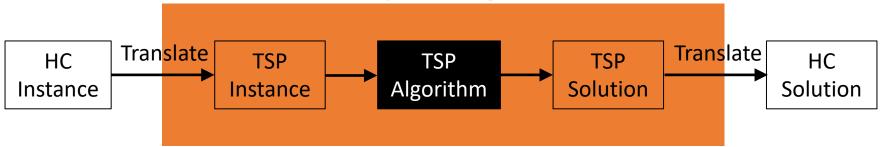
Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.

Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.

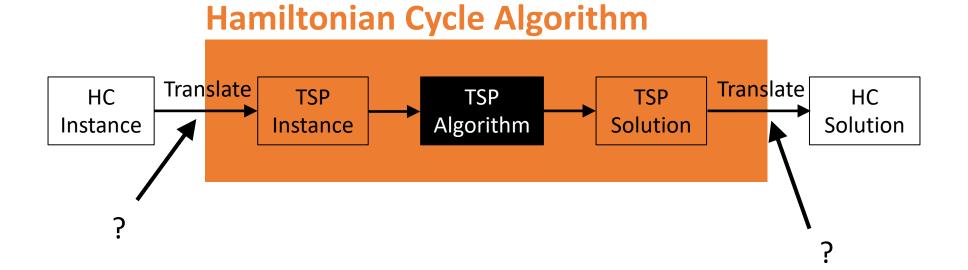
Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.

TSP: Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city once and returns to the origin city?

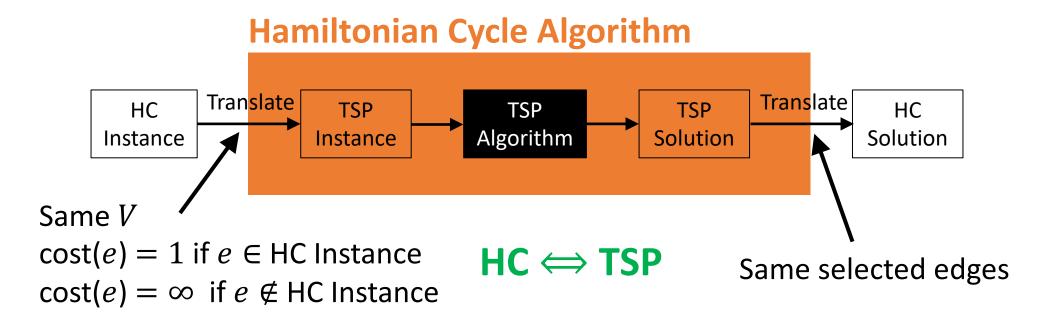
#### **Hamiltonian Cycle Algorithm**



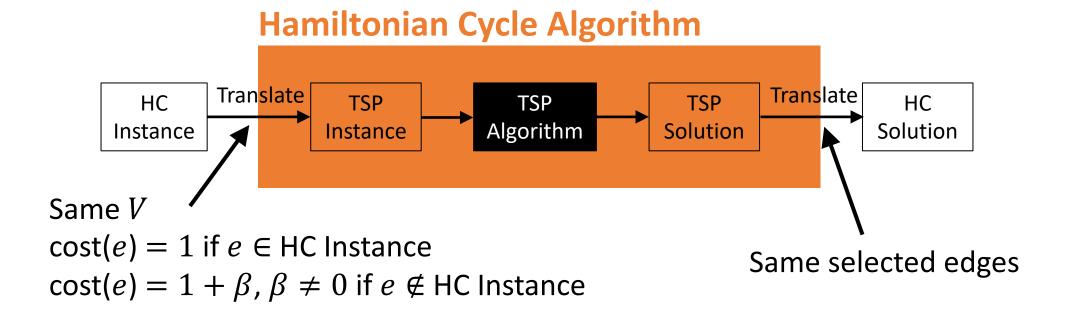
Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.



Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.



Hamiltonian Cycle: Given a graph, find a cycle that visits each vertex exactly once.



Translation:  $cost(e) = 1 \text{ if } e \in HC$ 

 $cost(e) = 1 + \beta, \beta \neq 0 \text{ if } e \notin HC$ 

Translation:  $cost(e) = 1 \text{ if } e \in HC$ 

 $cost(e) = 1 + \beta, \beta \neq 0 \text{ if } e \notin HC$ 

If G = (V, E) has a Hamiltonian Cycle,  $OPT_{TSP} = ?$ 

Translation: cost(e) = 1 if  $e \in HC$ 

 $cost(e) = 1 + \beta, \beta \neq 0 \text{ if } e \notin HC$ 

If G = (V, E) has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

```
Translation: cost(e) = 1 if e \in HC

cost(e) = 1 + \beta, \beta \neq 0 if e \notin HC
```

```
If G = (V, E) has a Hamiltonian Cycle, OPT_{TSP} = |V|
If G = (V, E) does not have a Hamiltonian Cycle, OPT_{TSP} = ?
```

```
Translation: cost(e) = 1 if e \in HC
```

$$cost(e) = 1 + \beta, \beta \neq 0 \text{ if } e \notin HC$$

```
If G = (V, E) has a Hamiltonian Cycle, OPT_{TSP} = |V|
If G = (V, E) does not have a Hamiltonian Cycle, OPT_{TSP} \ge |V| + \beta
```

Translation:  $cost(e) = 1 \text{ if } e \in HC$ 

 $cost(e) = 1 + \beta, \beta \neq 0 \text{ if } e \notin HC$ 

If G = (V, E) has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ If G = (V, E) does not have a Hamiltonian Cycle,  $OPT_{TSP} \ge |V| + \beta$ 

Let A be an  $\alpha$ -approximation algorithm for TSP (i.e. ALG  $\leq \alpha$  OPT) Let G = (V, E) be input to Hamiltonian Cycle.

Let G',  $\beta = \alpha |V|$  be input to TSP.

Translation: 
$$cost(e) = 1$$
 if  $e \in HC$   $cost(e) = 1 + \beta$ ,  $\beta \neq 0$  if  $e \notin HC$ 

If  $G = (V, E)$  has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

If  $G = (V, E)$  does not have a Hamiltonian Cycle,  $OPT_{TSP} \geq |V| + \beta$ 

Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $ALG \leq \alpha$  OPT)

Let  $G = (V, E)$  be input to Hamiltonian Cycle.

Let  $G', \beta = \alpha |V|$  be input to TSP.

What happens when  $A$  runs on  $G', \beta$ ...

If  $G$  has a Hamiltonian Cycle?

 $ALG_A \leq \frac{?}{?}$ 

If  $G$  does not have a Hamiltonian Cycle?

 $ALG_A \geq \frac{?}{?}$ 

Translation: 
$$\cos(e) = 1$$
 if  $e \in HC$   $\cos(e) = 1 + \beta$ ,  $\beta \neq 0$  if  $e \notin HC$ 

If  $G = (V, E)$  has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

If  $G = (V, E)$  does not have a Hamiltonian Cycle,  $OPT_{TSP} \geq |V| + \beta$ 

Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $ALG \leq \alpha$  OPT)

Let  $G = (V, E)$  be input to Hamiltonian Cycle.

Let  $G', \beta = \alpha |V|$  be input to TSP.

What happens when  $A$  runs on  $G', \beta$ ...

If  $G$  has a Hamiltonian Cycle?

 $ALG_A \leq \alpha$  OPT  $= \alpha |V|$ 

If  $G$  does not have a Hamiltonian Cycle?

 $ALG_A \geq ?$ 

Translation: 
$$\cos(e) = 1$$
 if  $e \in HC$   $\cos(e) = 1 + \beta$ ,  $\beta \neq 0$  if  $e \notin HC$ 

If  $G = (V, E)$  has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

If  $G = (V, E)$  does not have a Hamiltonian Cycle,  $OPT_{TSP} \geq |V| + \beta$ 

Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $ALG \leq \alpha$  OPT)

Let  $G = (V, E)$  be input to Hamiltonian Cycle.

Let  $G', \beta = \alpha |V|$  be input to TSP.

What happens when  $A$  runs on  $G', \beta$ ...

If  $G$  has a Hamiltonian Cycle?

 $ALG_A \leq \alpha$  OPT  $= \alpha |V|$ 

If  $G$  does not have a Hamiltonian Cycle?

 $ALG_A \geq OPT$ 

Translation: 
$$\cos(e) = 1$$
 if  $e \in HC$   $\cos(e) = 1 + \beta$ ,  $\beta \neq 0$  if  $e \notin HC$ 

If  $G = (V, E)$  has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

If  $G = (V, E)$  does not have a Hamiltonian Cycle,  $OPT_{TSP} \geq |V| + \beta$ 

Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $ALG \leq \alpha$  OPT)

Let  $G = (V, E)$  be input to Hamiltonian Cycle.

Let  $G', \beta = \alpha |V|$  be input to TSP.

What happens when  $A$  runs on  $G', \beta$ ...

If  $G$  has a Hamiltonian Cycle?

 $ALG_A \leq \alpha$  OPT  $= \alpha |V|$ 

If  $G$  does not have a Hamiltonian Cycle?

 $ALG_A \geq OPT \geq |V| + \beta$ 

Translation: 
$$\cos(e) = 1$$
 if  $e \in HC$   $\cos(e) = 1 + \beta$ ,  $\beta \neq 0$  if  $e \notin HC$ 

If  $G = (V, E)$  has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

If  $G = (V, E)$  does not have a Hamiltonian Cycle,  $OPT_{TSP} \geq |V| + \beta$ 

Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $ALG \leq \alpha$  OPT)

Let  $G = (V, E)$  be input to Hamiltonian Cycle.

Let  $G', \beta = \alpha |V|$  be input to TSP.

What happens when  $A$  runs on  $G', \beta$ ...

If  $G$  has a Hamiltonian Cycle?

 $ALG_A \leq \alpha OPT = \alpha |V|$ 

If  $G$  does not have a Hamiltonian Cycle?

 $ALG_A \geq OPT \geq |V| + \beta = |V| + \alpha |V|$ 

Translation: 
$$\cos(e)=1$$
 if  $e\in HC$   $\cos(e)=1+\beta$ ,  $\beta\neq 0$  if  $e\notin HC$  If  $G=(V,E)$  has a Hamiltonian Cycle,  $\operatorname{OPT}_{TSP}=|V|$  If  $G=(V,E)$  does not have a Hamiltonian Cycle,  $\operatorname{OPT}_{TSP}\geq |V|+\beta$  Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $\operatorname{ALG}\leq \alpha$  OPT) Let  $G=(V,E)$  be input to Hamiltonian Cycle. Let  $G',\beta=\alpha|V|$  be input to TSP. What happens when  $A$  runs on  $G',\beta...$  If  $G$  has a Hamiltonian Cycle? 
$$\operatorname{ALG}_A\leq \alpha \operatorname{OPT}=\alpha|V|$$
 If  $G$  does not have a Hamiltonian Cycle? 
$$\operatorname{ALG}_A\geq \operatorname{OPT}\geq |V|+\beta=|V|+\alpha|V|=(1+\alpha)|V|$$

Translation: 
$$cost(e) = 1$$
 if  $e \in HC$   $cost(e) = 1 + \beta$ ,  $\beta \neq 0$  if  $e \notin HC$ 

If  $G = (V, E)$  has a Hamiltonian Cycle,  $OPT_{TSP} = |V|$ 

If  $G = (V, E)$  does not have a Hamiltonian Cycle,  $OPT_{TSP} \geq |V| + \beta$ 

Let  $A$  be an  $\alpha$ -approximation algorithm for TSP (i.e.  $ALG \leq \alpha$  OPT)

Let  $G = (V, E)$  be input to Hamiltonian Cycle.

Let  $G', \beta = \alpha |V|$  be input to TSP.

What happens when  $A$  runs on  $G', \beta$ ...

If  $G$  has a Hamiltonian Cycle?

 $ALG_A \leq \alpha$  OPT  $= \alpha |V|$ 

If  $G$  does not have a Hamiltonian Cycle?

 $ALG_A \geq OPT \geq |V| + \beta = |V| + \alpha |V| = (1 + \alpha) |V| > \alpha |V|$ 

```
Let G', \beta = \alpha |V| be input to TSP and run A:

If G has a Hamiltonian Cycle,

ALG_A \leq \alpha |V|

If G does not have a Hamiltonian Cycle,

ALG_A > \alpha |V|
```

```
Let G', \beta = \alpha \mid V \mid be input to TSP and run A:

If G has a Hamiltonian Cycle,

ALG_A \leq \alpha \mid V \mid

If G does not have a Hamiltonian Cycle,

ALG_A > \alpha \mid V \mid
```

```
HamiltonianCycleFinder(G)
Let A be a TSP \alpha-approximation algorithm
Let \beta = \alpha |V| and run A on G', \beta
```

```
Let G', \beta = \alpha |V| be input to TSP and run A:
      If G has a Hamiltonian Cycle,
          ALG_A \leq \alpha |V|
      If G does not have a Hamiltonian Cycle,
          ALG_A > \alpha |V|
HamiltonianCycleFinder(G)
    Let A be a TSP \alpha-approximation algorithm
    Let \beta = \alpha |V| and run A on G', \beta
    if ALG_A \leq \alpha |V|
       return cycle found
    else
       return false
```

```
HamiltonianCycleFinder(G)
Let A be a TSP \alpha-approximation algorithm
Let \beta = \alpha \, |V| and run A on G', \beta
if ALG_A \leq \alpha \, |V|
return cycle found
else
return false

Is this a problem?
```

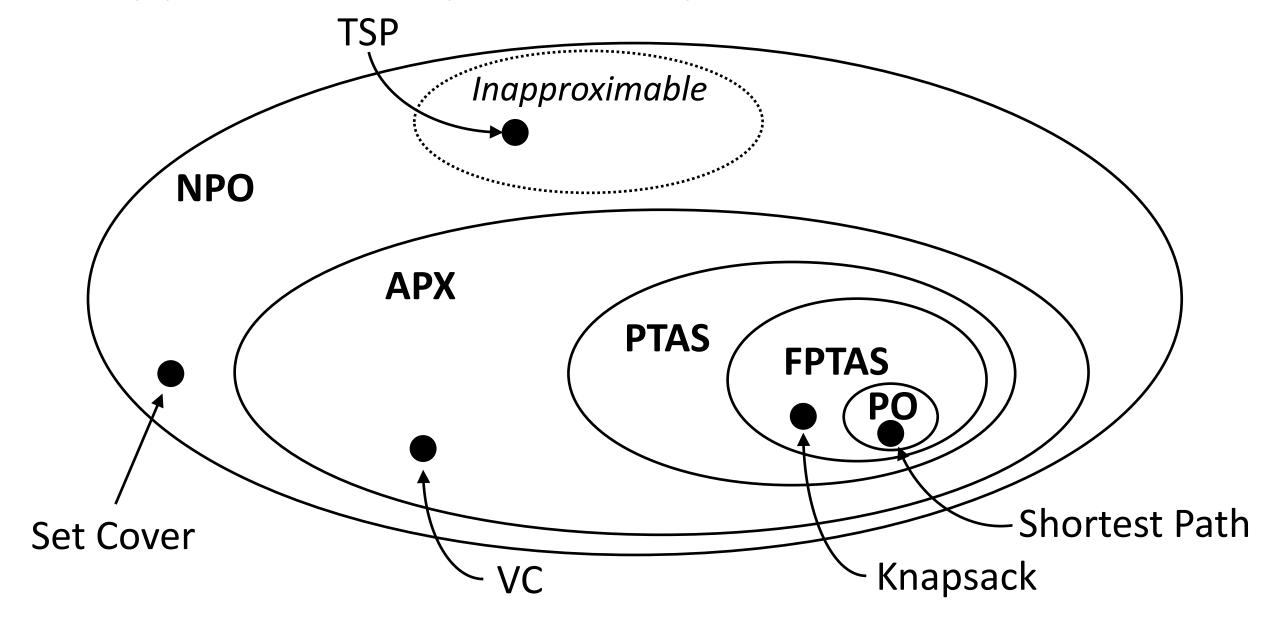
```
HamiltonianCycleFinder(G)
   Let A be a TSP \alpha-approximation algorithm
   Let \beta = \alpha |V| and run A on G', \beta
   if ALG_A \leq \alpha |V|
      return cycle found
   else
      return false
         Is this a problem?
            Yes! Any approximation algorithm for TSP will solve
            the NP-Complete Hamiltonian Cycle problem!
```

```
HamiltonianCycleFinder(G)
   Let A be a TSP \alpha-approximation algorithm
   Let \beta = \alpha |V| and run A on G', \beta
   if ALG_A \leq \alpha |V|
      return cycle found
   else
      return false
          Is this a problem?
             Yes! Any approximation algorithm for TSP will solve
             the NP-Complete Hamiltonian Cycle problem!
             \therefore \exists poly time approx alg for TSP, unless P = NP
```

```
HamiltonianCycleFinder(G)
Let A be a TSP \alpha-approximation algorithm
Let \beta = \alpha \, |V| and run A on G', \beta
if ALG_A \leq \alpha \, |V|
return cycle found
else
return false
Why is this the case?
```

```
HamiltonianCycleFinder(G)
   Let A be a TSP \alpha-approximation algorithm
   Let \beta = \alpha |V| and run A on G', \beta
   if ALG_A \leq \alpha |V|
      return cycle found
   else
      return false
         Why is this the case?
             Any approx alg for TSP is required to be valid, and a
             valid output is a Hamiltonian Cycle.
```

# Approximability Hierarchy



#### Integer Linear Programming

#### Suppose one could write an ILP for TSP:

```
x_{ij} = \left\{egin{array}{ll} 1 & 	ext{the path goes from city } i 	ext{ to city } j \ 0 & 	ext{otherwise} \end{array}
ight.
For i = 1, ..., n, let u_i be a dummy variable, and finally take c_{ij} to be the distance from city i to city j.
      \min \sum_{i=1}^n \sum_{j 
eq i, j=1}^n c_{ij} x_{ij}:
              egin{aligned} i = 1 & j 
eq i, j = 1 \ x_{ij} \in \{0,1\} & i,j = 1, \dots, n; \ u_i \in \mathbf{Z} & i = 2, \dots, n; \ \sum_{i=1, i 
eq j}^n x_{ij} = 1 & j = 1, \dots, n; \ \sum_{j=1, j 
eq i}^n x_{ij} = 1 & i = 1, \dots, n; \ u_i - u_j + n x_{ij} \le n - 1 & 2 \le i 
eq n; \end{aligned}
                 0 \le u_i \le n-1 2 \le i \le n.
                                                                                                                                                                                    From: Wikipedia
```

#### Integer Linear Programming

#### Suppose one could write an ILP for TSP:

```
x_{ij} = \begin{cases} 1 & \text{the path goes from city } i \text{ to city } j \\ 0 & \text{otherwise} \end{cases} For i = 1, \ldots, n, let u_i be a dummy variable, and finally take c_{ij} to be the distance from city i to city j. \min \sum_{i=1}^n \sum_{j \neq i, j=1}^n c_{ij} x_{ij} : x_{ij} \in \{0, 1\} \qquad \qquad i, j = 1, \ldots, n; u_i \in \mathbf{Z} \qquad \qquad i = 2, \ldots, n; \sum_{i=1, i \neq j}^n x_{ij} = 1 \qquad \qquad j = 1, \ldots, n; \sum_{j=1, j \neq i}^n x_{ij} = 1 \qquad \qquad i = 1, \ldots, n; u_i - u_j + n x_{ij} \leq n - 1 \qquad 2 \leq i \neq j \leq n; 0 \leq u_i \leq n - 1 \qquad 2 \leq i \leq n. From: Wikipedia
```

What could you conclude?

### Integer Linear Programming

#### Suppose one could write an ILP for TSP:

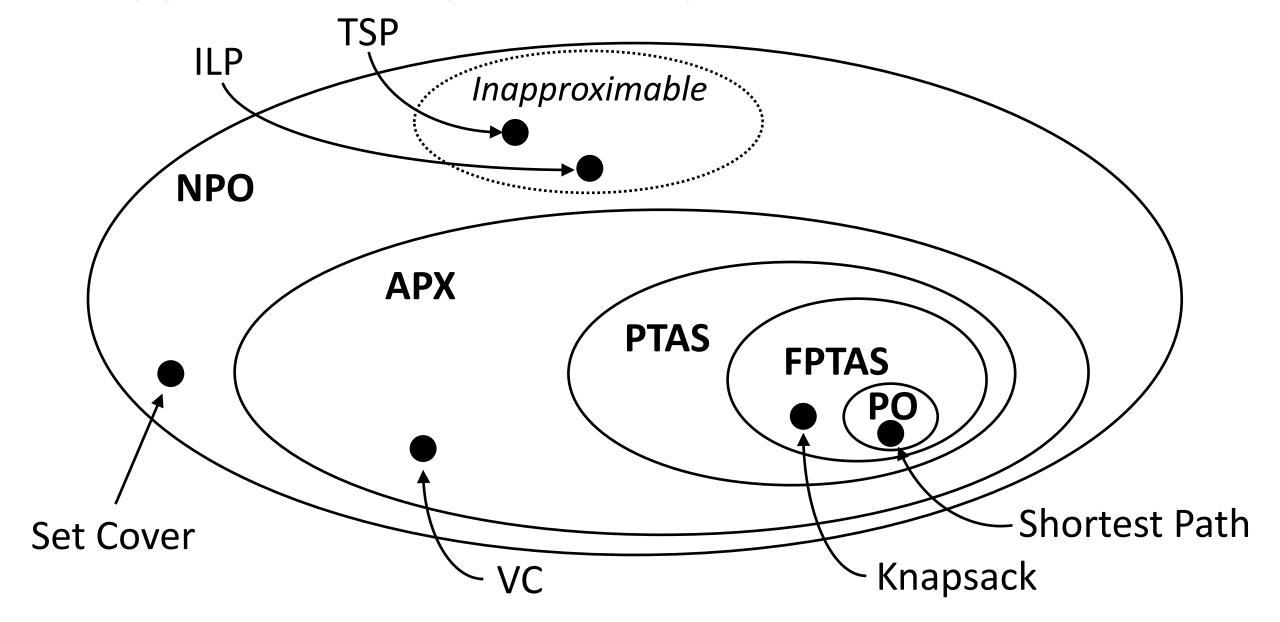
```
x_{ij} = \begin{cases} 1 & \text{the path goes from city } i \text{ to city } j \\ 0 & \text{otherwise} \end{cases} For i=1,\ldots,n, let u_i be a dummy variable, and finally take c_{ij} to be the distance from city i to city j. \min \sum_{i=1}^n \sum_{j\neq i,j=1}^n c_{ij} x_{ij} \colon x_{ij} \in \{0,1\} \qquad \qquad i,j=1,\ldots,n; u_i \in \mathbf{Z} \qquad \qquad i=2,\ldots,n; \sum_{i=1,i\neq j}^n x_{ij} = 1 \qquad \qquad j=1,\ldots,n; \sum_{j=1,j\neq i}^n x_{ij} = 1 \qquad \qquad i=1,\ldots,n; u_i - u_j + n x_{ij} \le n-1 \qquad 2 \le i \ne j \le n; 0 \le u_i \le n-1 \qquad 2 \le i \le n. From: Wikipedia
```

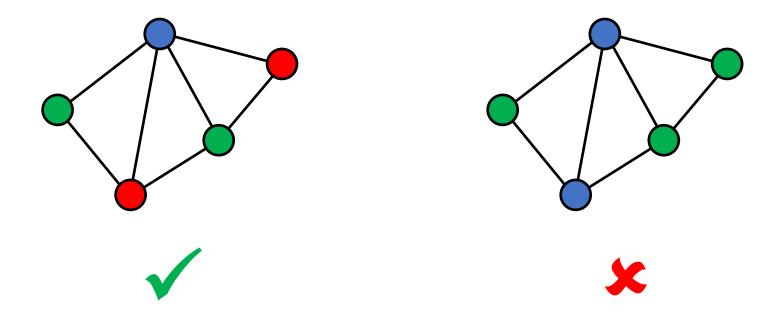
#### What could you conclude?

If TSP in inapproximable, solving ILPs must be too!

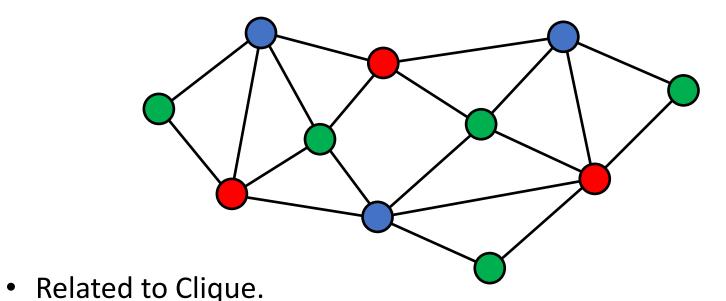
(Otherwise an approximation algorithm for ILPs would provide an approximation algorithm for TSP.)

## Approximability Hierarchy



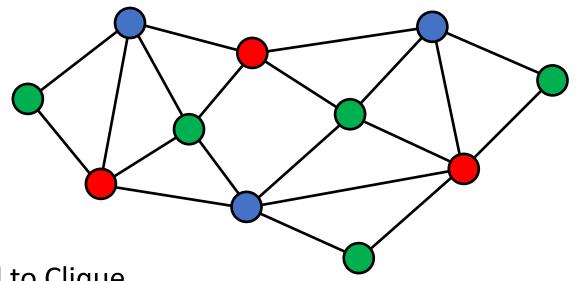


Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.



• Influenced by vertex degree.

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

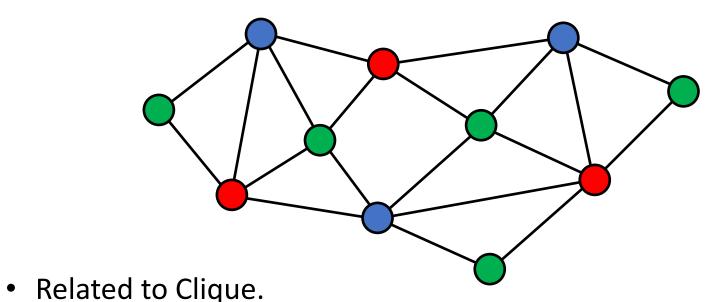


n	$\chi(n)$
0	?

Related to Clique.

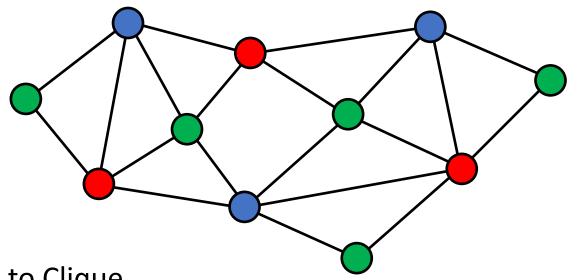
Influenced by vertex degree.

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.



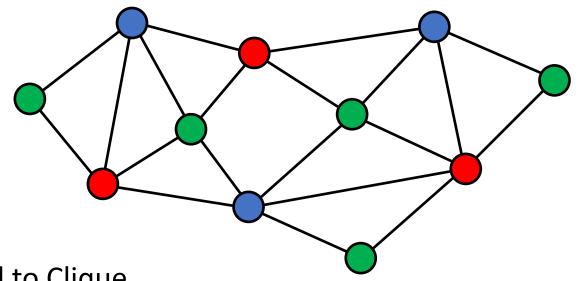
n	$\chi(n)$
0	<b>√</b>

Influenced by vertex degree.



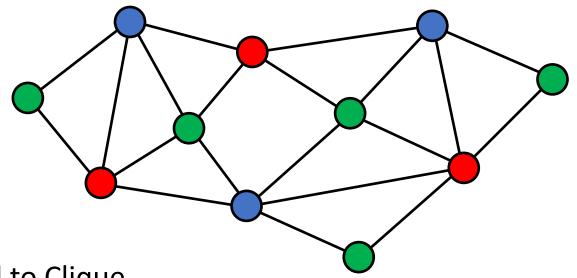
n	$\chi(n)$
0	<b>✓</b>
1	?

- Related to Clique.
- Influenced by vertex degree.



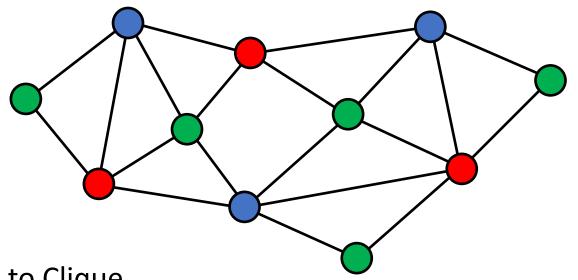
$\chi(n)$
<b>√</b>
<b>√</b>

- Related to Clique.
- Influenced by vertex degree.



$\chi(n)$
<b>√</b>
$\checkmark$
?

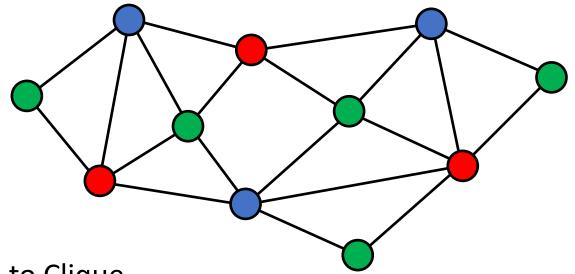
- Related to Clique.
- Influenced by vertex degree.



n	$\chi(n)$
0	✓
1	$\checkmark$
2	$\checkmark$
2	

- Related to Clique.
- Influenced by vertex degree.

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.



•	Re	lated	to	Cl	iq	ue	•
---	----	-------	----	----	----	----	---

Influenced by vertex degree.

n	$\chi(n)$
0	<b>√</b>
1	$\checkmark$
2	$\checkmark$
3	*
4	*
:	

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

#### NP-Hard to determine (for $k \geq 3$ ):

- Is graph k-colorable?
- What is the minimum colorable value?
- Is graph colorable with k or fewer colors?
- Related to Clique.
- Influenced by vertex degree.

n	$\chi(n)$
0	✓
1	$\checkmark$
2	$\checkmark$
3	x
4	×
•	

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

$$ALG \le \left(\frac{4}{3} - \varepsilon\right) OPT$$

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

$$ALG \le \left(\frac{4}{3} - \varepsilon\right)OPT = \left(\frac{4}{3} - \varepsilon\right)3 = 4 - 3\varepsilon$$

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

$$ALG \le \left(\frac{4}{3} - \varepsilon\right)OPT = \left(\frac{4}{3} - \varepsilon\right)3 = 4 - 3\varepsilon < 4$$

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

$$ALG \le \left(\frac{4}{3} - \varepsilon\right)OPT = \left(\frac{4}{3} - \varepsilon\right)3 = 4 - 3\varepsilon < 4 \Rightarrow ALG \le 3$$

Minimum Graph Coloring: Given graph, find the smallest number of colors such that each vertex can be assigned a color and neighboring vertices do not share colors.

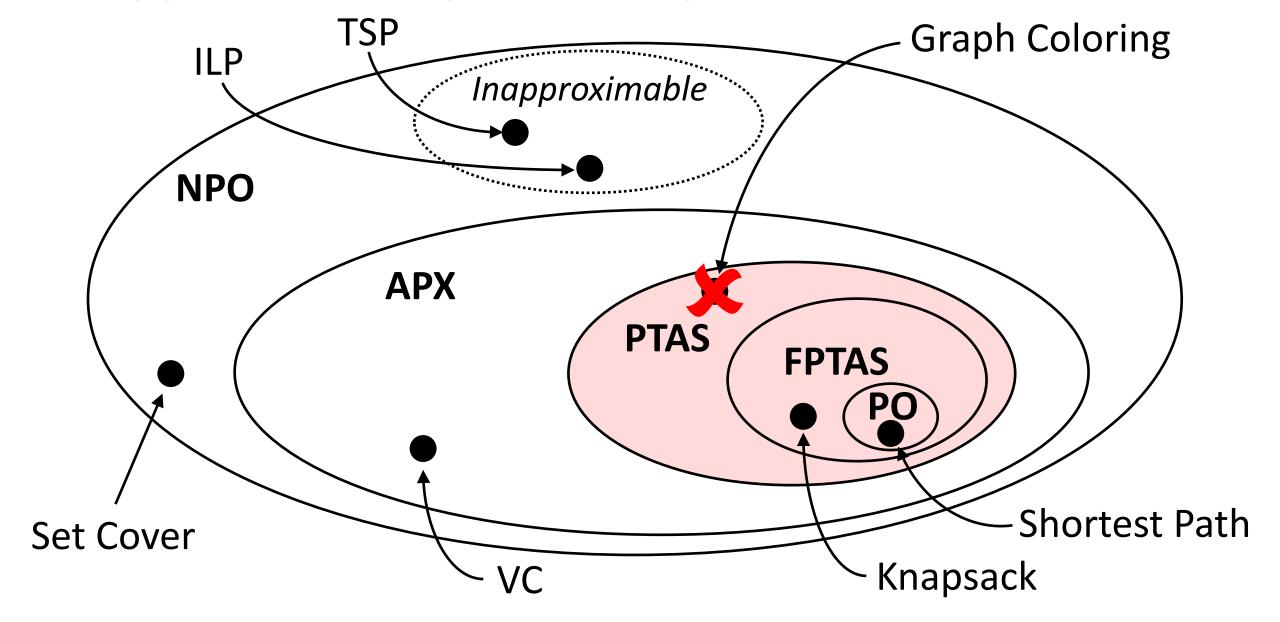
Suppose we had a  $\left(\frac{4}{3} - \varepsilon\right)$ -approximation algorithm for the problem.

What happens when we run it on a graph with  $\chi(G) = 3$ ?

$$ALG \le \left(\frac{4}{3} - \varepsilon\right)OPT = \left(\frac{4}{3} - \varepsilon\right)3 = 4 - 3\varepsilon < 4 \Rightarrow ALG \le 3$$

Thus, we could determine if a graph is 3-colorable ⇒ algorithm can't exist.

## Approximability Hierarchy

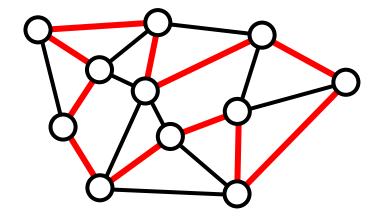


TSP: Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city once and returns to the origin city?

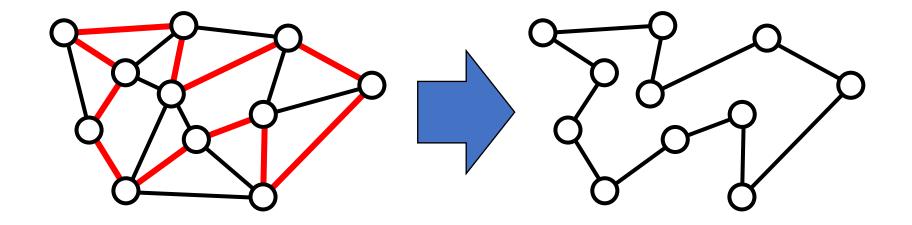
TSP: Given a list of cities and the distances between each pair of cities (satisfying the triangle inequality), what is the shortest possible route that visits each city once and returns to the origin city?

$$dist(u, v) \leq dist(u, w) + dist(w, v)$$

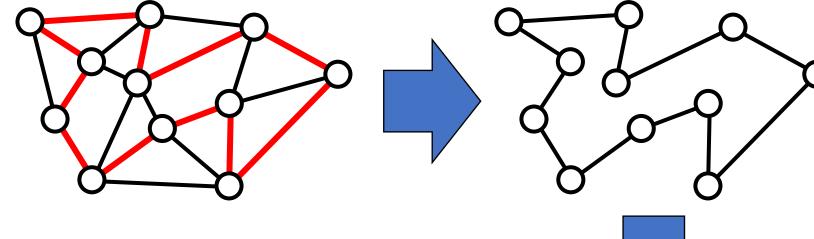
- 1. Easy to compute.
- 2. Related to TSP.
- 3. Lower bound on OPT.



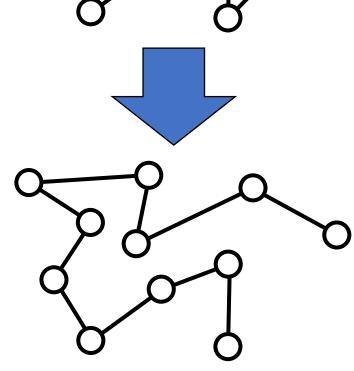
- 1. Easy to compute.
- 2. Related to TSP.
- 3. Lower bound on OPT.

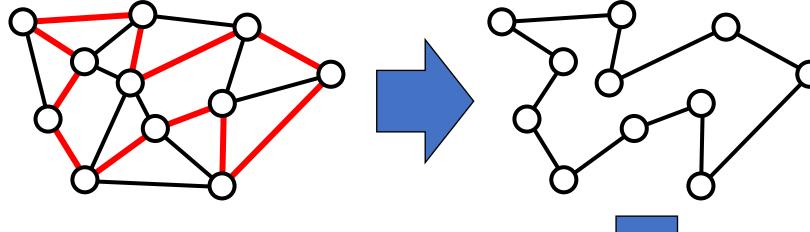


- 1. Easy to compute.
- 2. Related to TSP.
- 3. Lower bound on OPT.



- 1. Easy to compute.
- 2. Related to TSP.
- 3. Lower bound on OPT.

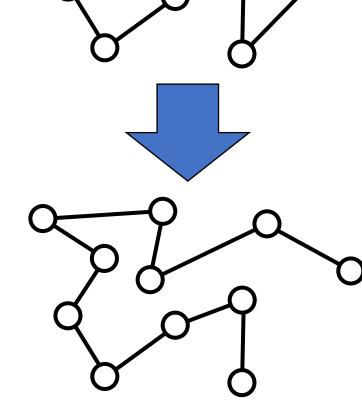


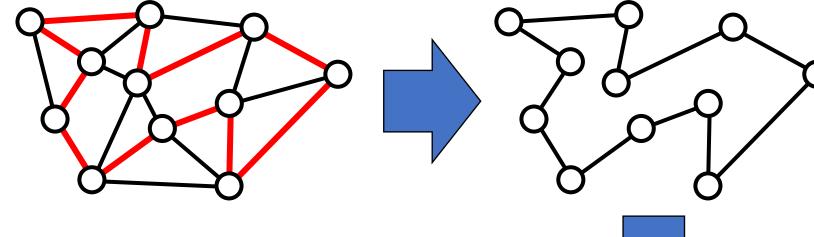


Find some structure that is:

- 1. Easy to compute.
- 2. Related to TSP.
- 3. Lower bound on OPT.

What is this?

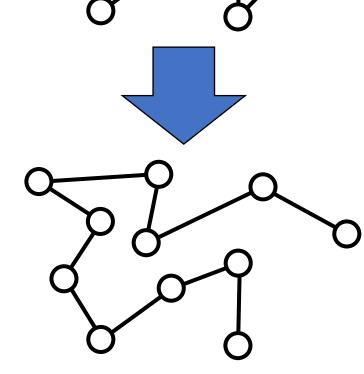




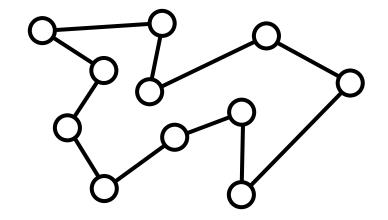
Find some structure that is:

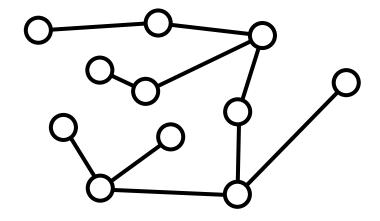
- 1. Easy to compute.
- 2. Related to TSP.
- 3. Lower bound on OPT.

What is this?
Spanning Tree



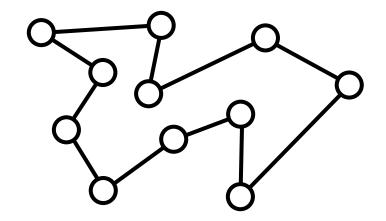
Relationship between OPT and cost of MST?

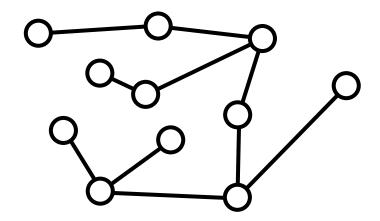




Relationship between OPT and cost of MST?  $OPT \ge cost(MST)$ 

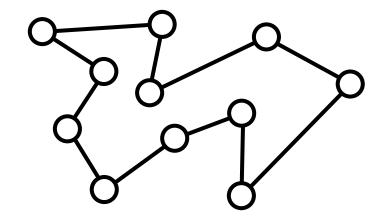
How to turn MST into tour of cities?

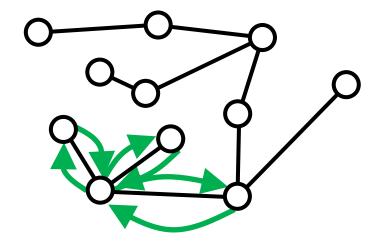




Relationship between OPT and cost of MST?  $OPT \ge cost(MST)$ 

How to turn MST into tour of cities? What is the cost of this tour?

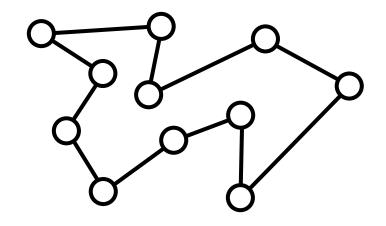


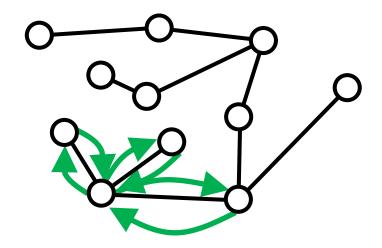


Relationship between OPT and cost of MST?  $OPT \ge cost(MST)$ 

How to turn MST into tour of cities? What is the cost of this tour? ALG = 2 cost(MST)

Relationship between ALG and OPT?





Relationship between OPT and cost of MST?  $OPT \ge cost(MST)$ 

How to turn MST into tour of cities?

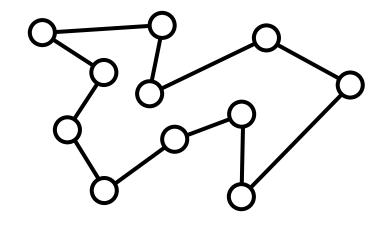
What is the cost of this tour?

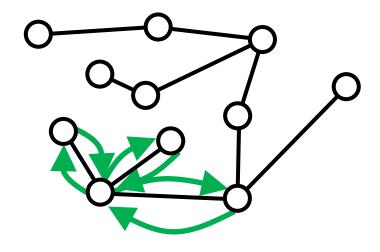
$$ALG = 2 cost(MST)$$

Relationship between ALG and OPT?

$$ALG = 2 cost(MST) \le 2 OPT$$

Any problems?





Relationship between OPT and cost of MST?  $OPT \ge cost(MST)$ 

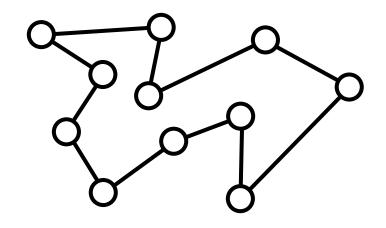
How to turn MST into tour of cities? What is the cost of this tour?

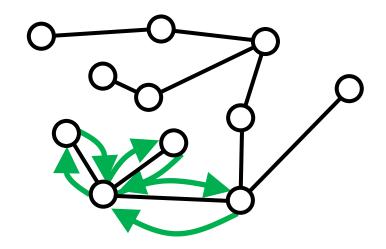
$$ALG = 2 cost(MST)$$

Relationship between ALG and OPT?

$$ALG = 2 cost(MST) \le 2 OPT$$

How can we eliminate double visits (without messing up the cost)?





Relationship between OPT and cost of MST?  $OPT \ge cost(MST)$ 

How to turn MST into tour of cities? What is the cost of this tour?

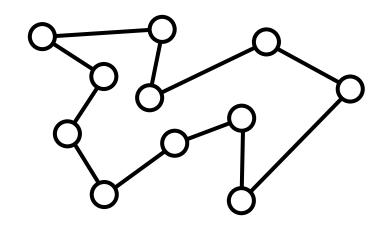
$$ALG = 2 cost(MST)$$

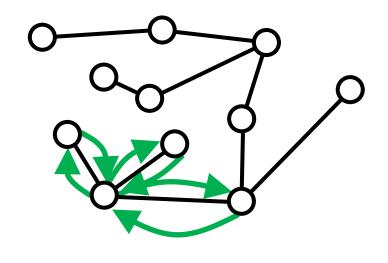
Relationship between ALG and OPT?

$$ALG = 2 cost(MST) \le 2 OPT$$

How can we eliminate double visits (without messing up the cost)?

Skip to next unvisited vertex. Can only decrease cost (triangle inequality).  $dist(u, v) \leq dist(u, w) + dist(w, v)$ 





## Approximability Hierarchy

