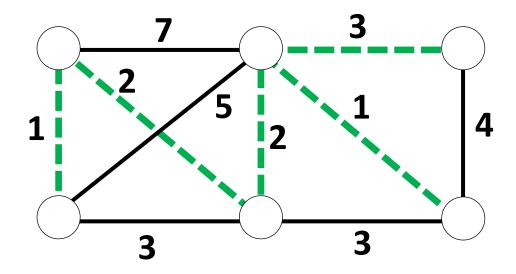
Closest Pair of Points CSCI 532

Algorithm: Add the edge with smallest weight, that does not create a cycle.

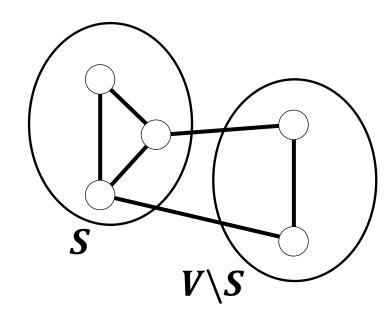


What are some questions we may have about the algorithm?

- 1. Is the solution valid? (Does it actually find a spanning tree?)
- 2. What is the running time?
 - 3. Is the solution optimal?

<u>Lemma:</u> Suppose that S is a subset of nodes from G = (V, E). Then, the cheapest edge e between S and $V \setminus S$ is part of every MST.

Proof:



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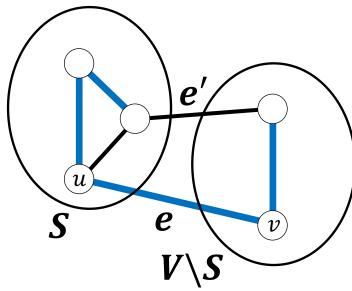
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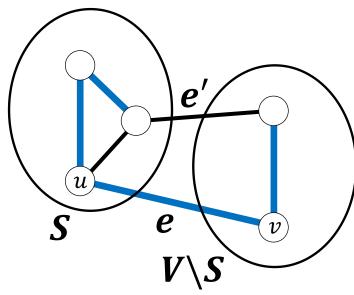
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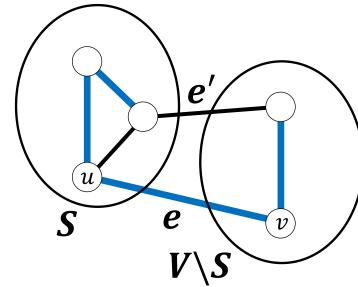
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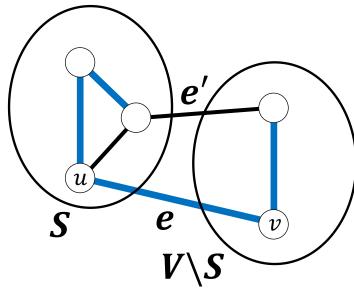
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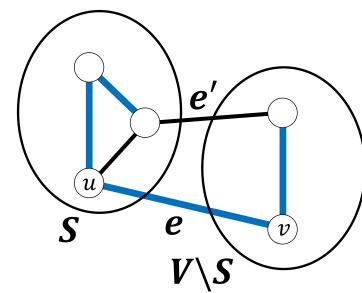
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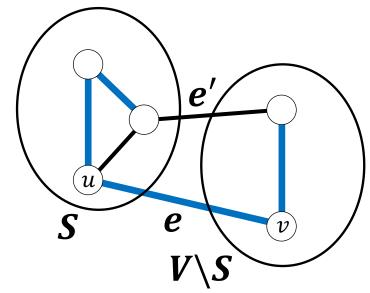
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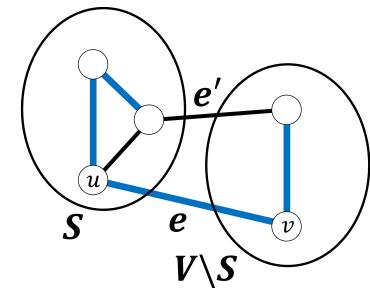
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 \Rightarrow Every MST must include e.



Algorithm: Add the edge with smallest weight, that does not create a cycle.

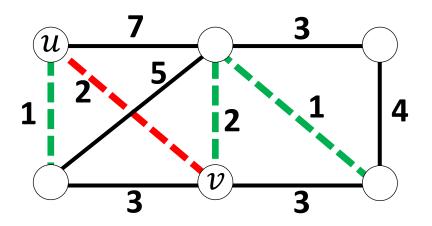
<u>Proof of optimality:</u> Let G = (V, E), and $T \subseteq E$ be the set of edges resulting from Kruskal's algorithm.

55

Algorithm: Add the edge with smallest weight, that does not create a cycle.

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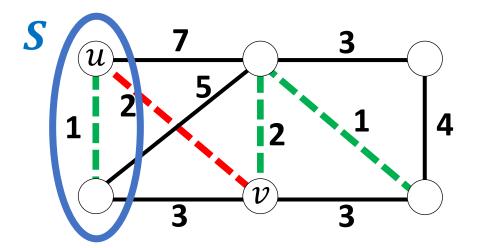
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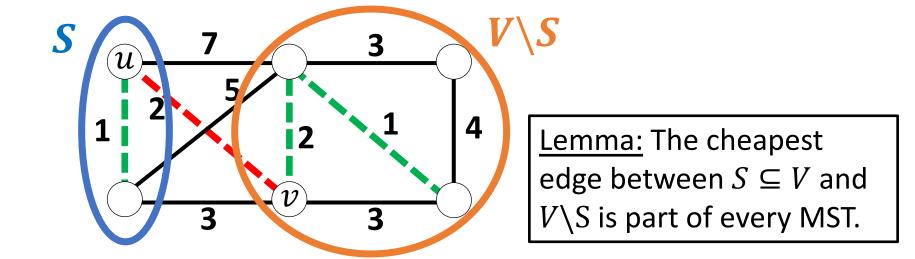
Consider the interation that some edge e = (u, v) is added by Kruskal's algorithm. Let S be the set of u and all nodes already connected to u. (or v and all nodes connected to v)



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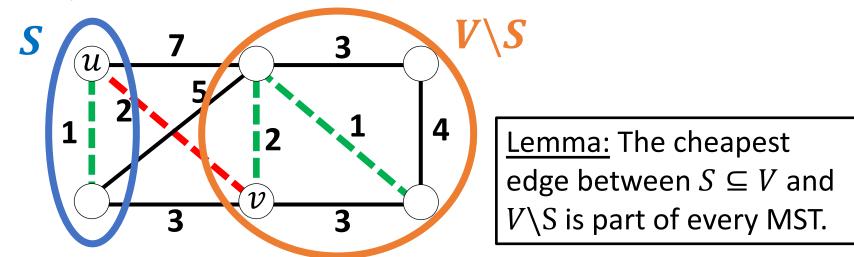
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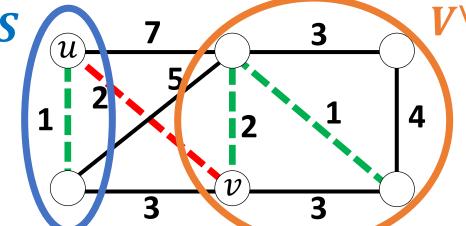


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the MST.

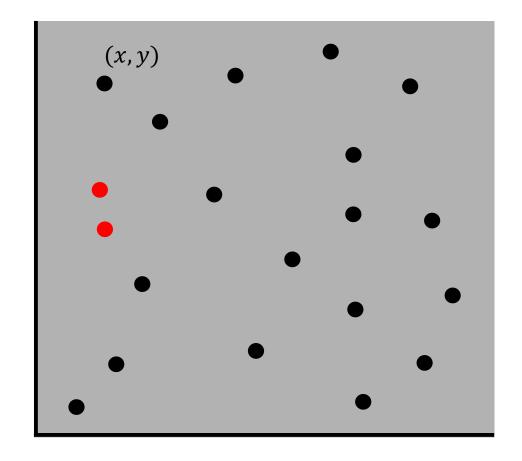


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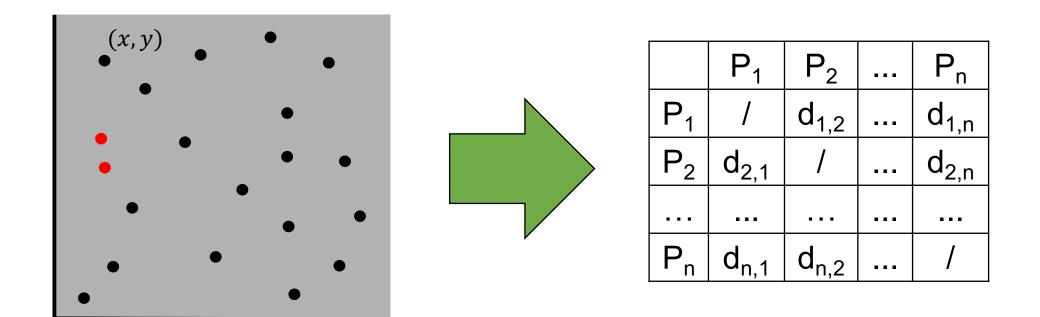
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Thus, every edge found by Kruskal's algorithm is part of the MST, and since the edges found form a spanning tree, it is the MST.



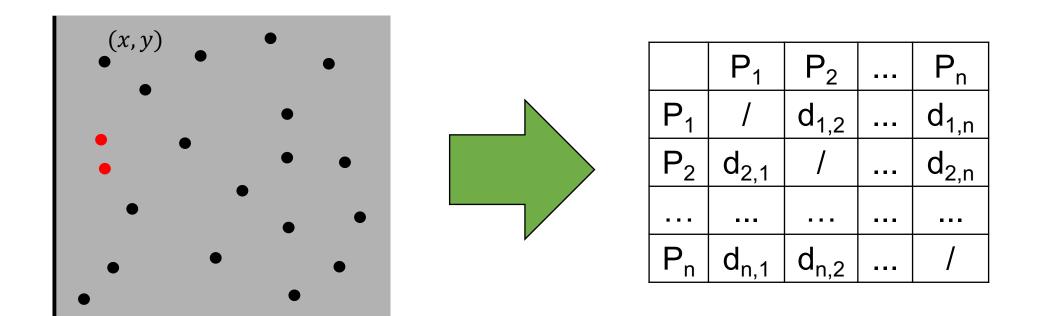
Given n points, find a pair of points with the smallest distance between them.



Simple solution:

- 1. Compute distance for each pair.
- 2. Select smallest.

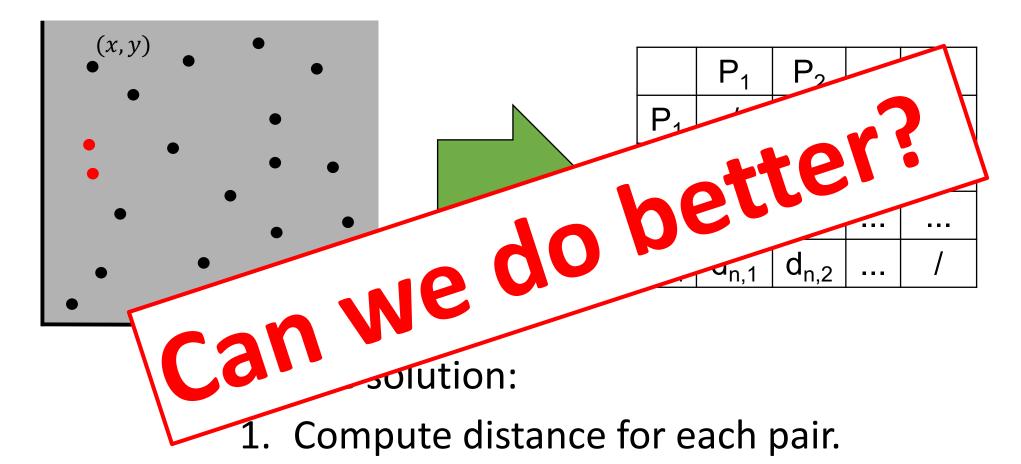
Running Time = ?



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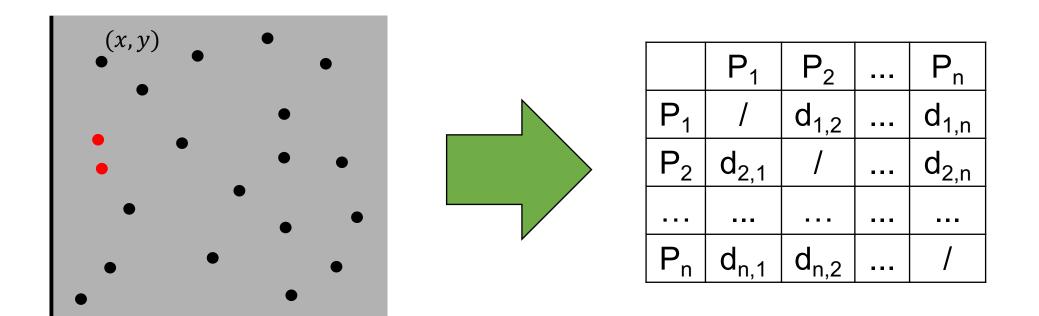
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Running Time =
$$O(n^2)$$



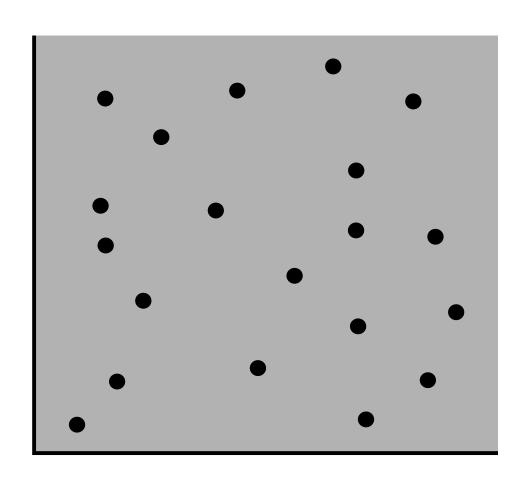
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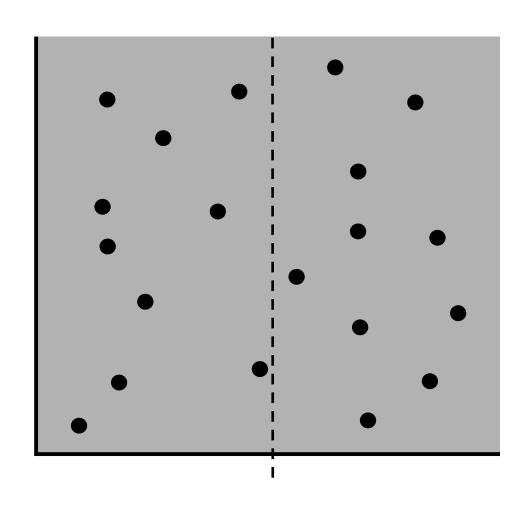


Divide and Conquer Algorithms:

- Divide into subproblems that are smaller instances of the original.
- "Conquer" the subproblems by solving them recursively.
- Combine subproblem solutions into solution for original problem.

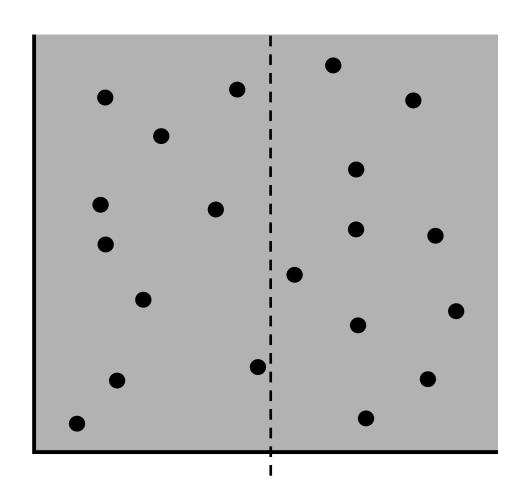


How can we make the problem smaller and easier?

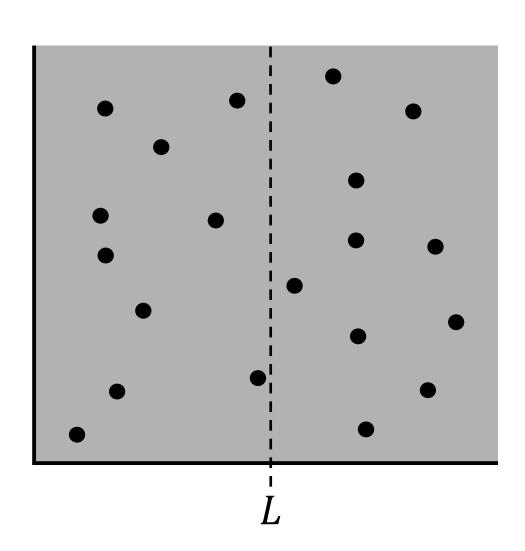


How can we make the problem smaller and easier?

Split it up!

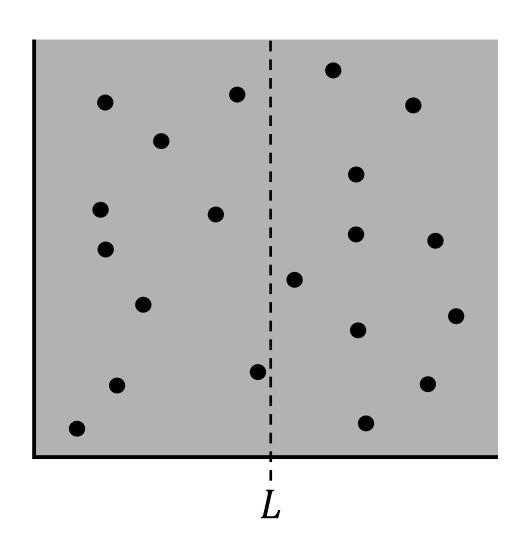


Divide: How can we draw line so that half of the points are on each side?



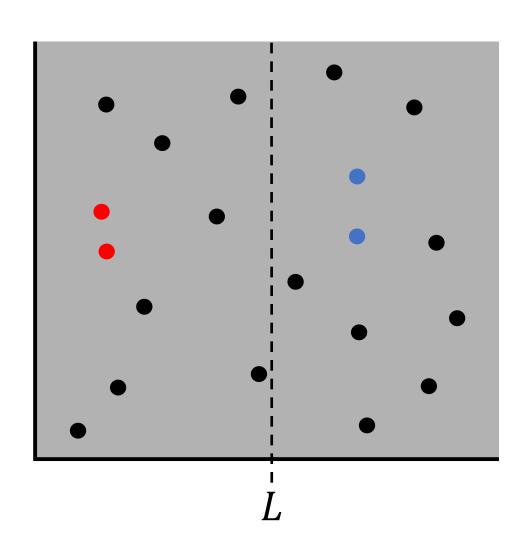
Divide: How can we draw line so that half of the points are on each side?

- 1. Sort by x-coordinate.
- 2. Put *L* at median value.

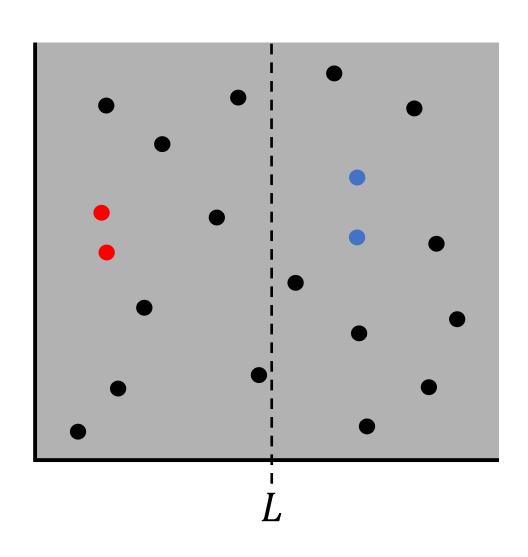


Conquer:

Recursively find closest pairs on each side¹.

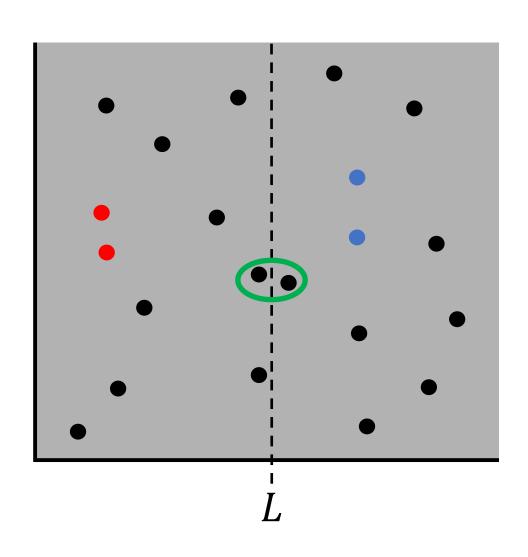


Combine: If we had the closest left pair and the closest right pair, how do we determine actual closest?



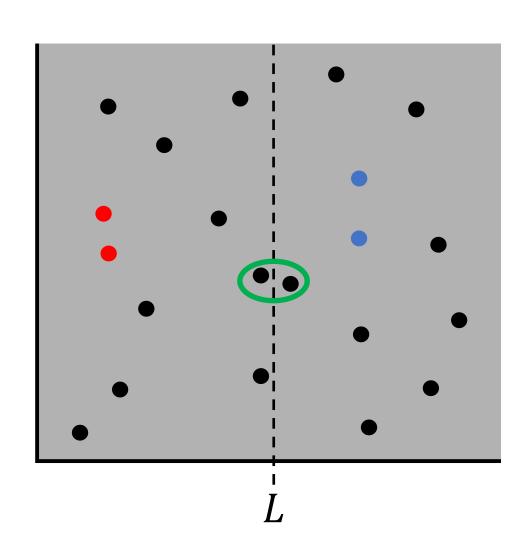
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1. Return minimum of: d_{left} , d_{right} .



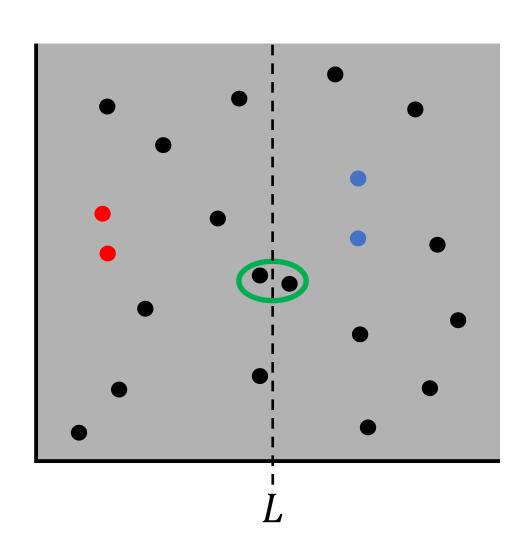
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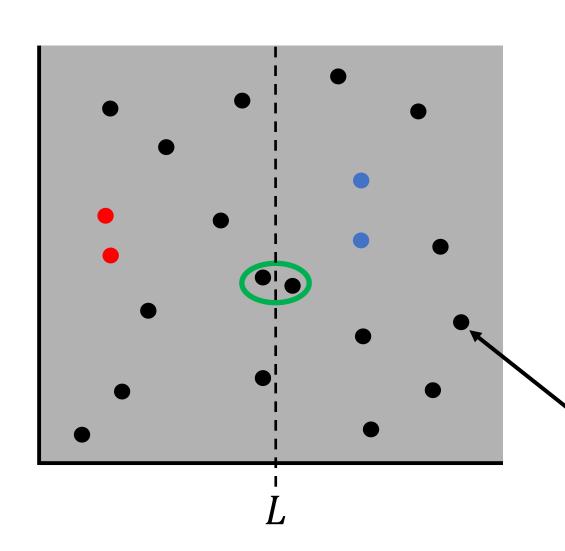
Combine: If we had the closest left pair and the closest right pair, how do we determine actual closest?

1. Return minimum of: d_{left} , d_{right} , $d_{\text{min_straddle}}$.



How should we search for "straddle points"?

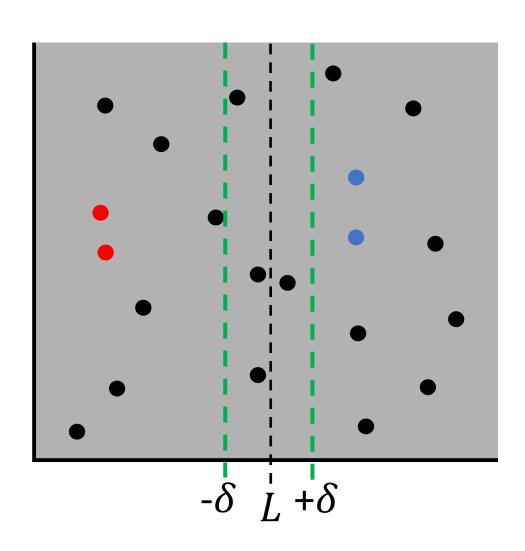
We know $\delta = \min(d_{\text{left}}, d_{\text{right}})$.



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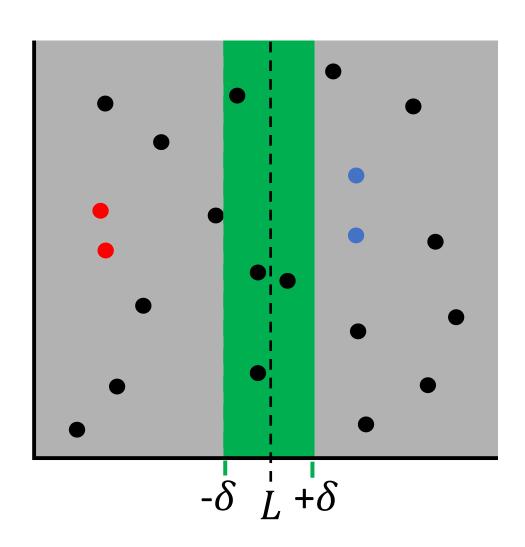
We know $\delta = \min(d_{\text{left}}, d_{\text{right}})$.

Do we need to consider this point when looking for straddle points?



Rule: We only need to hunt for straddle points at most δ away from L.

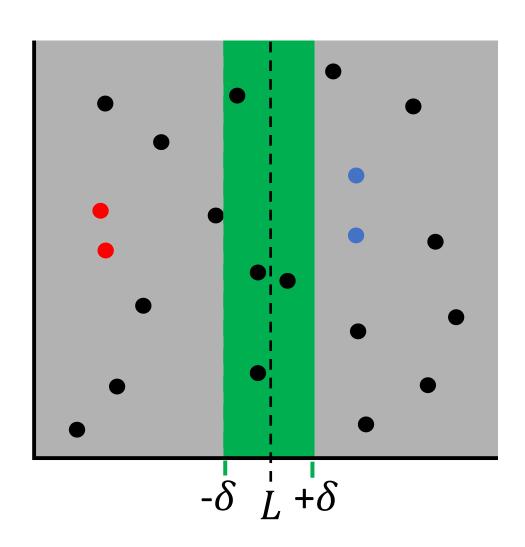
Reason: Points outside $L \pm \delta$ cannot reach the other side in less than δ .



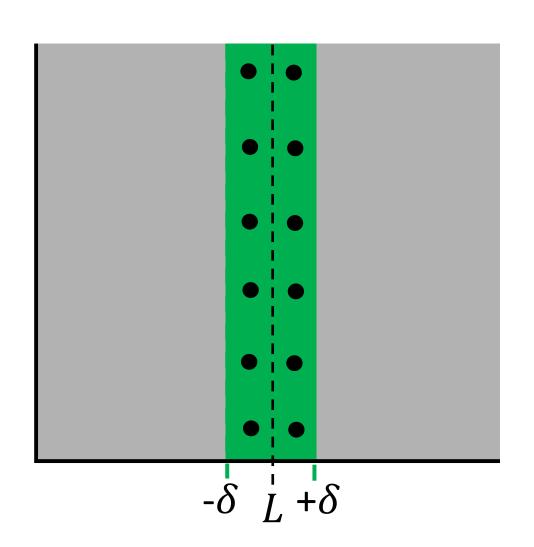
Rule: We only need to hunt for straddle points at most δ away from L.

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Let **S** be the set of straddle points.

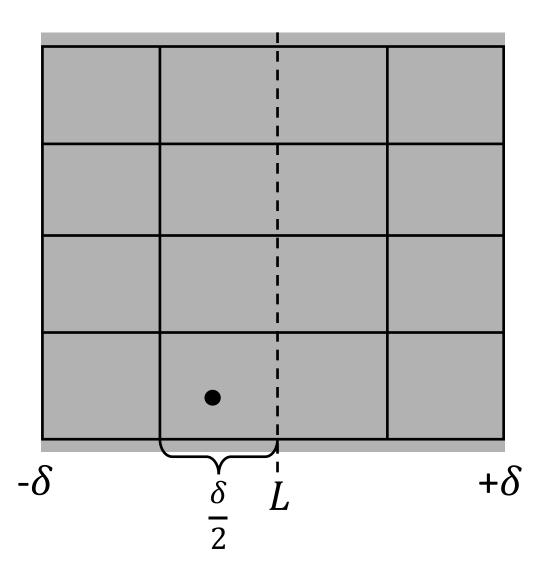


Can we just compare all left straddle points to all right straddle points?



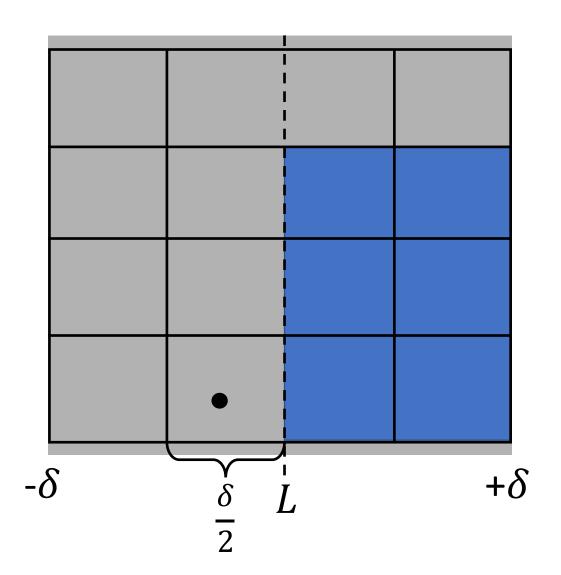
Can we just compare all left straddle points to all right straddle points?

So, we need to reduce the number of straddle points we have to consider.



Divide *S* into $\frac{\delta}{2} \times \frac{\delta}{2}$ boxes.

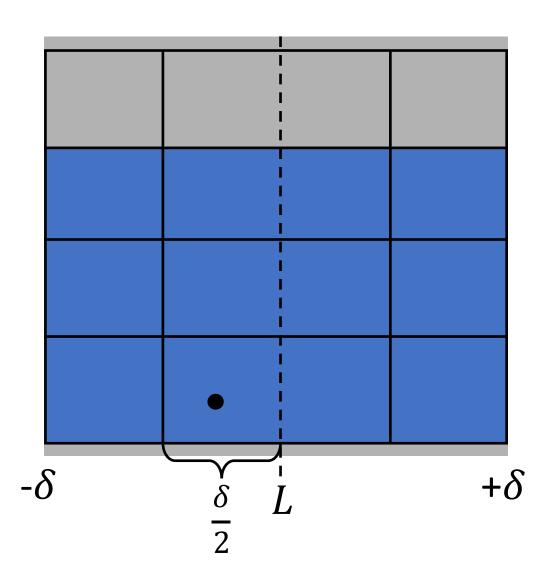
Can we focus our search to certain boxes?



Divide S into $\frac{\delta}{2} \times \frac{\delta}{2}$ boxes.

Can we focus our search to certain boxes?

Yes – we only care about points within δ .

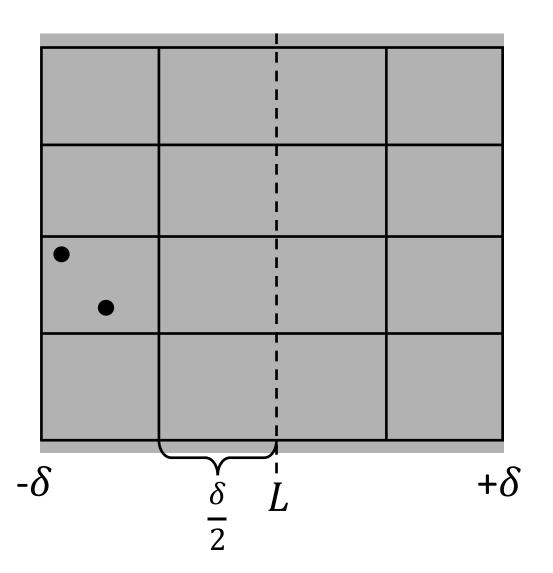


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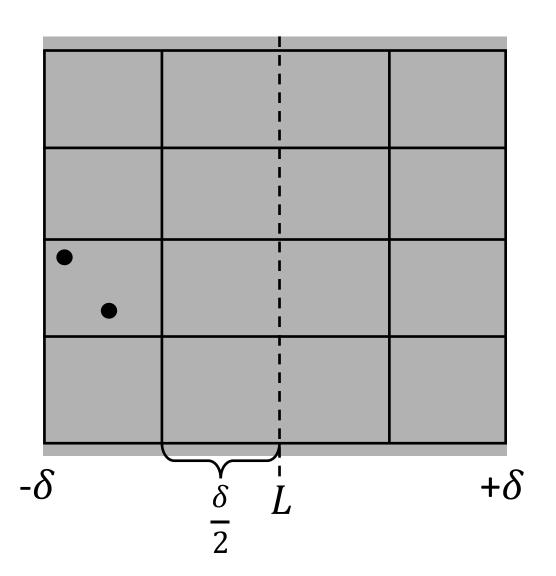
Can we focus our search to certain boxes?

Yes – we only care about points within δ .

This still gives us possibly lots of points to look at.



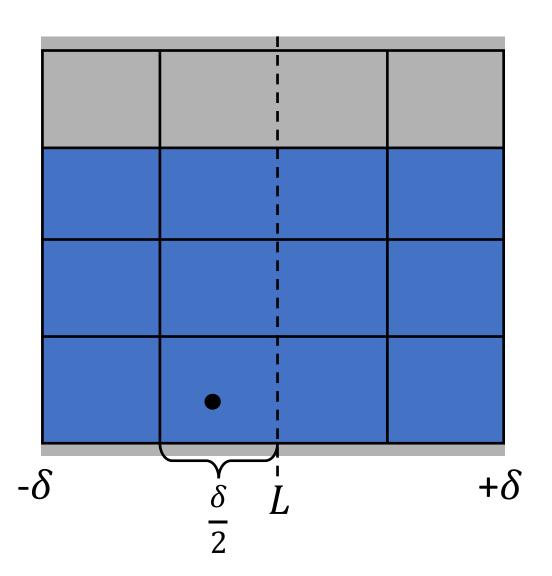
Can we have multiple points in one box?



Can we have multiple points in one box?

No. δ is the smallest distance on either side of L.

 \Rightarrow at most one point per box.

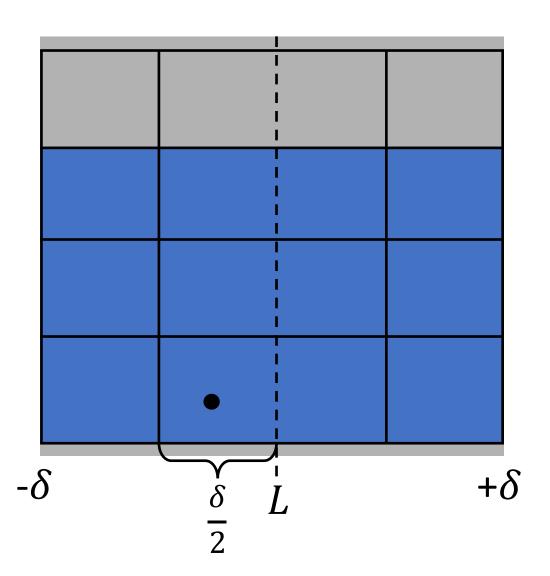


Only care about certain boxes

+ At most one point per box

Fixed number of points to check

- 1. Sort straddle points by *y* coordinate.
- 2. Only possible " δ -busting" points are the 11 points after our point being considered.



Only care about certain boxes

+ At most one point per box

Fixed number of points to check

Straddle point hunting:

$$O(n^2) \longrightarrow O(n \log n)$$